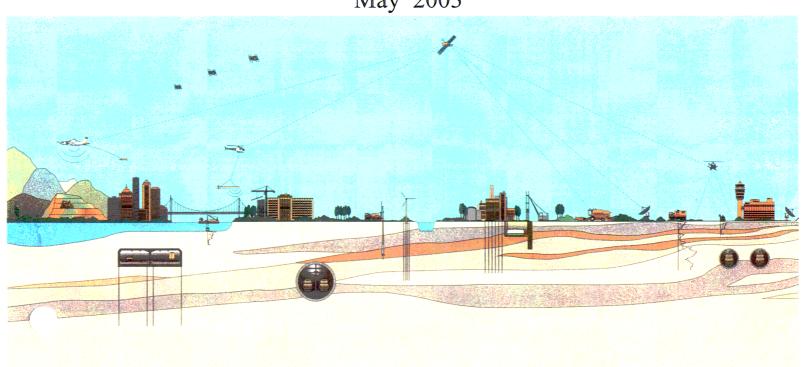




### U.S. Army Corps Of Engineers St. Louis District Grand Canyon Monitoring & Research Center

### SURVEY CONTROL REPORT

Grand Canyon, Arizona
LIDAR Survey for the South Canyon & Eminence Sites
Contract No. DACW43-02-D-0505
JCLS Job #03-6027
May 2003



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### 1.0 FLI-MAP® SYSTEM DESCRIPTION

### JOHN CHANCE LAND SURVEYS, INC.

### 1.1 FLI-MAP®

The following is a brief description of how FLI-MAP® integrates the use of LiDAR technology and GPS to meet the challenge for a fast and accurate means of aerial surveying. The mobile FLI-MAP® system was designed by John E Chance & Associates. The system description will be for the mobile FLI-MAP® system, which can be attached to several types of helicopters.

### 1.1.1 System description FLI-MAP®

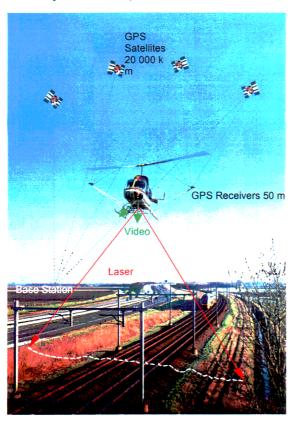


Figure 1: FLI-MAP® system

The basic concept is that a helicopter flies over the corridor to be surveyed, collecting precise GPS measurements, platform attitude, laser ranges, and imagery data.

The LiDAR sensor scans the terrain and objects directly below the helicopter at a rate of 10 000 points a second. The scan width is 1.15 times the helicopter height above the ground. The terrain directly below and forward of the aircraft is imaged with high-resolution video cameras, and recorded with a digital time stamp. Figure 1 is a graphical presentation of the FLI-MAP® system.

The final post processed output, including the video from the FLI-MAP system, includes XYZ positions of the laser returns. The data density that is required to differentiate railway infrastructure components such as rails, mile posts, signals, switches, electrification wires, masts, etc. is at least 10 points per m<sup>2</sup>. These railway infrastructure components are identified by patterns of points with spatial relationships. Thus, the FLI-MAP® system integrates several main systems into a high-tech survey tool and the various subsystems are described

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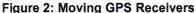
(dual

provide

### **Positioning System**

below:

FLI-MAP® incorporates two **GPS** (moving) receivers frequency L1/L2) and multiple ground reference GPS receivers. These GPS receivers, both moving and ground reference, record the dual frequency carrier phase and pseudo range measurements from each satellite. The two airborne moving receivers (with separate antennas) redundancy check on the post-processed kinematic DGPS aircraft position. Figure 2 shows the two moving GPS receivers mounted on the helicopter.



### **Navigation System**

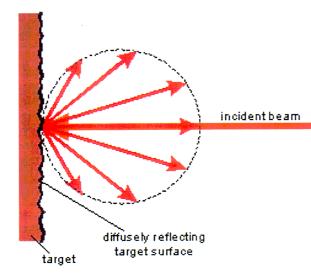
Omnistar® satellite receivers are used to collect standard RTCM-104 differential corrections, which provide a sub-meter accuracy of the helicopter for real-time pilot navigation. A higher level of accuracy and reliability of the position (< 10cm) can be calculated during post processing.

### **Attitude System**

A solid state Inertial Measurement Unit (IMU) is used to measure instantaneous pitch, roll and heading, as well as accelerations of the platform in three dimensions. These measurements are used by the integrated Inertial Navigation System (INS) to calculate accurate attitude of the helicopter at every sampling location. The INS also provides redundancy checks on the aircraft position during the post processing.

### **Laser System**

The scanning laser is a custom designed eye safe, reflectorless rangefinder using near middle Infrared light and is capable of measuring first return ranges from 20 - 250 meters. The laser light is generally reflected omni-directionally from an uncooperative target according to Lambert's cosine law, see Figure 3.



The reflectivity of typical materials encountered is given in Table 1

Table 1: Material Reflectivity							
MATERIAL	REFLECTIVITY						
White paper	up to 100%						
Snow	80-90%						
Limestone, clay	up to 75%						
Deciduous trees	typ. 60%						
Coniferous trees	typ. 30%						
Carbonate sand	57 - 41%						
Beach sands	typ. 50%						
Concrete, smooth	24%						
Asphalt with pebbles	17%						
Lava	8%						
Black neoprene	5%						
Black rubber tire wall	2%						
(Values shown for 900 nm wavelength)							

Figure 3: Uncooperative Target Reflection

which results in 10 000 points per second.

contains 200 distance Every scan measurements and has a width of 60 degrees. Each scan record also contains referencing, timing, laser attitude, data verification/error detection information and intensity information which provides an active infrared imaging capability. Operationally, the laser scans at a rate of 50 times per second,

### Video System

FLI-MAP is equipped with two high resolution, broadcast quality, color video cameras, producing 750 horizontal TV lines with the 3-chip CCD. The video data is recorded directly to hard drives in MPEG format. The down looking camera records approximately the same area that is laser scanned and has a zoom factor of approximately x1. The forward-looking camera, mounted in an oblique position, has a fixed focal length with a zoom factor of approximately x1.5. The precise UTC time is encoded on each frame of video, allowing for accurate correlation with the laser data. All pilot / operator communications and voice notes are recorded on the audio track of the MPEG recorder for archiving and aiding in image interpretation.

### **Digital Still System**

FLI-MAP is also equipped with two digital, ½" CCD, high-resolution still cameras set in the down and forward-looking perspectives. Both cameras incorporate an IEEE 1394, Firewire interface, capturing 1 frame per second per camera. The down looking camera has a zoom factor of x1 and the forward-looking camera has a zoom factor of approximately x1.5. At a typical flight altitude of 50 meters, the down looking camera delivers images with a resolution of approximately 4 centimeters per pixel.

### **Display and Acquisition System**

The FLI-MAP® system can direct and guide the pilot along predetermined survey flight lines, using <u>LED</u> light bars to indicate course deviation, both horizontally and vertically. The horizontal course is determined by the navigation and positioning systems and the scanning laser Average Ground Level (AGL) feature provides the vertical course. The pilot and operator can view both the down-looking and forward-looking video on a flat screen color display, while the operator has a dedicated laptop for control and status monitoring of the system during operations.

The airborne processing system is a multiple Intel-based PC, which provides airborne data management, sensor control, and navigation processing. The measurements such as GPS pseudo ranges and carrier phase, laser scan records, and the real-time differential and INS solutions, are stored on removable memory cards.

### Aircraft Integration

As the FLI-MAP® system is a modular design, it can be mounted to various types of helicopters. For this purpose the system is divided into two main parts, the sensor platform and the Electronic Control Unit (ECU). The sensor platform is mounted to standard cargo connection points below the helicopter. This platform contains the laser, IMU and video cameras and two specially designed extensions on which the GPS antennas are mounted. The ECU contains all the necessary data collecting and processing equipment such as GPS and Omnistar receivers, the INS, video recorders, computer board and data storage facilities. The box (19 in.) is fixed inside the helicopter and is connected to the sensor platform by means of an 'umbilical cord'. Figure 4 shows the sensor platform and the ECU.



Figure 4: Helicopter with Mobile Sensor Platform and EMU Onboard

### 2.0 PROJECT DESCRIPTION

### 2.1 Project Description

In May 2003, John Chance Land Surveys, Inc. was contracted to St. Louis District Corps of Engineers for acquiring digital elevation data along two projects in northern Arizona for the Grand Canyon Monitoring & Research Center & USGS utilizing the FLI-MAP® LIDAR system. The two projects are the Eminence and South Canyon areas.

The purpose for the surveys is to obtain a precise survey and develop a digital terrain model (DTM) of the projects to be surveyed for the purpose of determining volumes or obtaining other engineering data. The survey will be accomplished utilizing aerial topographic laser surveying techniques (LIDAR) to develop and identify all right of way characteristics and develop digital terrain models as necessary to obtain profiles of road crossing, piers, and other physical features.

The deliverables for this project consist of the following:

- a. A survey narrative shall be produced in the form of a letter type report detailing all aspects of the LIDAR flight, including a description of the fieldwork and detailed office data processing procedures. The description shall include location, navigation and control, operations, all survey logs and data sheets used, any difficulties with the survey, and the method of resolution of the difficulties shall be documented. Two copies of the report for each of the two projects shall be provided.
- b. The contractor shall provide an interpretation and analysis of the results of the survey, including data quality, coverage of the area, and a summary of the findings. This summary shall be included in the transmittal letter documenting the electronic data delivered as a result of the survey. Two copies of each project shall be provided.
- c. Fli-Map laser data will be delivered on DVD with the latest version of the FLIP-7 software. Upgrades to FLIP-7 software may be necessary for current users. Also, high-resolution color digital video imagery (360 x 240 pixels) that is time coded to the Fli-Map data will be delivered of the entire route in mpeg format. Three videos should be submitted including forward and down perspective with the third video being a digitized double zoom down video. Two copies of the Fli-Map laser data and digital video imagery shall be submitted on DVD. Additionally, two copies of ASCII data for the entire project shall be submitted on CD-ROM for use within other software that may not read the FLIP7 compressed data format.
- d. Two copies of two data sets are required. Both a cleaned and edited raw Fli-Map data set and a thinned to approximately 5% data set shall be delivered in ASCII format. The entire data set shall be filtered to produce a bare earth model and delivered in ASCII format. ASCII data file size shall be no greater than 200,000 points. Both a hard copy and digital index of the data file shall be produced.
- e. The contractor will provide up to 24 hours of training for up to six engineers or technicians or their representatives in the use of FLIP7 software. The training will be conducted at the Contractors office location. Transportation costs and per diem costs will be paid by government personnel attending the training. FLIP7 technical support shall be provided for 24 hours of help (for each engineer or technician) by telephone over a one-year period. Responses to requests for technical support shall be made during normal business hours within 2 business days of initial inquiry. New releases or upgrades of the FLIP7 software shall be provided to the St. Louis District of the U.S. Arm Corps of Engineers and the GCMRC, Flagstaff, AZ at no cost of the government for a period of one year.

f. A metadata file at least minimally compliant with the Federal Geographic Data Committee (FGDC) Content Standards for Digital Geospatial Metadata. The COE will provide a Metadata generation package (CORPSMET) to generate these files upon request by the Contractor or the Contractor can use software of their choice as long as the FGDC compliant Metadata is produced as specified in 2.b above.

### 3.0 DATA COLLECITON SUMMARY

### 3.1 Data Collection Summary

The following are daily reports of the field activities during job reconnaissance and data collection. Further detailed information about the data collection flights can be found in section 5.5 "Flight Information".

<u>Friday, May 23, 2003:</u> Five employees of John Chance Land Surveys, Inc., Connie Landry, Chris Guillory, Faron Olivier, Terry Richard, and Steve Broussard arrived in Tusayan, AZ.

Saturday, May 24, 2003: Connie, Chris, Faron, Terry, and Steve located all of the control for the two projects. Blaine Thibodeaux and Morgan Reed arrived by plane.

<u>Sunday, May 25, 2003:</u> Crew performed the static survey for the both projects. The FLI-MAP system was installed on the helicopter and a test flight was performed.

Monday, May 26, 2003: The first day of data collection consisted of two flights. The first flight consisted of data collection for the South Canyon Site. It consisted of approximately 20.8 miles of data collection during a 1 hr 34 min flight. The second flight consisted of approximately 24 miles of data collection for the Eminence Site during a 1 hr 32 min flight. The base stations used for these flights were "EMIN", "SCTH", & "BCTH". The laser data was processed, verified for coverage and transferred onto CD-ROM. The digital video & Imagery was verified and transferred onto DVD. All data was collected at an approximate altitude of 100 meters with an average ground speed of 17 meters per second.

<u>Tuesday, May 27, 2003:</u> The second data of data collection consisted of one flight. The 1 hr 28 min flight consisted of approximately 19.74 miles of data collection for the Eminence Site. The Eminence Site was recollected due to GPS gaps from the previous day. The base stations used for these flights were "EMIN", "SCTH", & "BCTH". The laser data was processed, verified for coverage and transferred onto CD-ROM. The digital video & Imagery was verified and transferred onto DVD. All data was collected at an approximate altitude of 100 meters with an average ground speed of 17 meters per second.

Wednesday, May 27, 2003: The FLI-MAP® LIDAR system and the crew were demobilized. Data collection for this job was complete. Faron, Terry, and Steve started driving back to Lafayette, La. Connie and Chris drove to Albuquerque, NM to catch plane. Blaine and Morgan flew back to Lafayette, LA.

Thursday, May 29, 2003: Connie and Chris arrive in Lafayette, LA. Faron, Terry, and Steve still driving to Lafayette.

Friday, May 30, 2003: Faron, Terry, and Steve arrive in Lafayette, LA.

FIELD	<b>PERSONNEL</b>
	LLICOITIE

TYPLE	PERSONNEL	COMPANY
Project Supervisor	Connie Landry	John Chance Land Surveys, Inc.
Project Supervisor	Faron Olivier	John Chance Land Surveys, Inc.
Data Processor	Terry Richard	John Chance Land Surveys, Inc.
Department Manager	Blaine Thibodeaux	John Chance Land Surveys, Inc.
Senior Development Engineer	Morgan Reed	John Chance Land Surveys, Inc.
FLI-MAP System Operator	Steve Broussard	John Chance Land Surveys, Inc.
Survey Technician/Data Processor	Chris Guillory	John Chance Land Surveys, Inc.
Pilot	Walter Wiser	Papillion Helicopters

### 4.0 DATA PROCESSING REPORT

### 4.1 Data Processing Report

<u>Initial Processing:</u> FLI-MAP® processing consists of merging the GPS data collected at the control stations with the GPS, INS, and laser data collected in the helicopter during the flight. The processing of this information produces XYZ coordinates in Flip7®, software written by John E. Chance & Associates, which allows the viewing and data manipulation of FLI-MAP® data. The sequential steps are described as follows:

- GPS and INS data are "unpacked" from the format in which they are collected in the helicopter and are placed in the appropriate data tree structure which separates the data recorded from the two helicopter receivers and the real-time inertial data recorded by the IMU sensor atop the primary laser.
- Once the primary, secondary, GPS, and IMU data are placed in the correct directories, GPS data from the ground control station(s) and the two helicopter receivers are post-processed using OTF kinematic techniques to produce a best fit location of the two helicopter antennas every one half second.
- Position vectors are calculated between the two helicopter antennas and the CRP (common reference point) located in the primary laser using lever arm offsets and real-time IMU data for 3D-angle orientation.
- The aircraft position and attitude data is then merged with the laser information in CHANCE's Flip7® software package to produce XYZ data sets and perform orthometric height modeling.

Utilizing Flip7®, the data is processed to produce the following:

- A complete XYZ data set by computing a XYZ coordinate for 100% of the laser returns. This file represents all physical features detected by the laser.
- Each laser point has a northing, easting, and elevation assigned to it as well as an intensity value and UTC time. Flip7® can then link the laser points with the corresponding time on the video so that the digital image (laser data) and color video of an object in question can be viewed easily.

<u>Field Processing</u>: FLI-MAP® data processing is started in the field to ensure coverage, accuracy, and quality of the data before de-mobilization may occur. All raw data as well as processed data is transferred onto CD-ROM.

### **DATA PROCESSING**

The data from each flight is processed to produce 3D positions of laser returns. The GPS data from the base stations and the primary navigation receiver on the helicopter is reduced kinematically to produce helicopter heading, pitch, and roll results every one half second. Combining this information with John Chance Land Survey's proprietary software, FLIP7, enables the data to be manipulated. A digital terrain model (DTM) can be extracted by classifying those "laser returns" which best define the terrain surface.

Within FLIP7, an appropriate coordinate system is set up and a filtering routine removes vegetation candidates from the data set. The remaining data points are contoured by laser file and remaining outliers are removed. This data is exported in ASCII files and can be read by most third party software formats.

The ASCII data is imported into Terramodel where the data is combined and linked and contoured. The data is then checked again for outliers. Once the DTM has been verified for accuracy the data is written to an appropriate ASCII file or files. These files were written out in a comma delimited file in an "easting, northing, elevation" format.

### PROCESSING OF THE SOUTH CANYON SITE

In order to have coverage of the South Canyon site JCLS flew one flight, 030526x1 to collect lidar data. This flight was processed in FLIP7 and filtered to remove vegetation from each lidar file. The data was processed in NAD 83 coordinates State Plain Zone 0202, Arizona Central. The out put coordinates are in meters. The data was next contoured to remove possible outliers. Then it was exported in ASCII format. The river edge was also digitized and exported as a dxf file as well as aerial panel points that were visible in the data set.

This file was imported into Terramodel where it was checked again for outliers and combined with all of the exported files to make one dtm file. The South Canyon area data was then separated into 21 files and exported in about 500,000 points per file sections. A dxf file of the river edge and the 21 areas were also exported at this time.

Data for the South Canyon site is burned onto a CD and includes 21 ASCII xyz files, dxf file, and an aerial panel points file.

### PROCESSING OF THE EMINENCE SITE

In order to have coverage of the Eminence site JCLS flew one flight, 030527x1 to collect lidar data. This flight was processed in FLIP7 and filtered to remove vegetation from each lidar file. The data was processed in NAD 83 coordinates State Plain Zone 0202, Arizona Central. The out put coordinates are in meters. The data was next contoured to remove possible outliers. Then it was exported in ASCII format. The river edge was also digitized and exported as a dxf file as well as aerial panel points that were visible in the data set.

This file was imported into Terramodel where it was checked again for outliers and combined with all of the exported files to make one dtm file. The Eminence area data was then separated into 20 files and exported in about 500,000 points per file sections. A dxf file of the river edge and the 20 areas were also exported at this time.

Data for the Eminence site is burned onto a CD and includes 20 ASCII xyz files, dxf file, metafile, and an aerial panel points file.

### **RAW LASER FILES**

JCLS also created ASCII raw xyz data files from FLIP7. These files contain raw processed laser returns so that the information could be imported into third party software. South Canyon (Flight 0526x1) and Eminence (Flight 0527x1) sites were burned each on a CD. The raw data are ASCII space delimited files in an "easting northing elevation" format.

### **VIDEO**

A forward and a down video were encoded and burned to DVD. The imagery is time stamped and can be driven through FLIP7 to correspond with FLIP7 processed laser information. The videos can also be viewed separate of FLIP7. The video data is burned on individual CD disk per flight and perspective (45 and 90) degree camera angles.

### **DELIVERABLES**

JCLS delivered two copies of the following information to

Engineer District, St. Louis, VEMVS\_ED\_S (Attn: Robert D. Mesko)
1222 Spruce Street
St. Louis, MO 63103-2833

- Latest Version of FLIP7 (Version 2003.07.04) (1CD)
- FLIP7 project files for flights.
  - o Flight 030526x1 (2 CDs)
  - o Flight 030527x1 (2 CDs)
- Final dtm files in files of approximately 500,000 points. Dxf file, metafile, and aerial panel points file.
  - o Flight 030526x1 (2 CDs)
  - o Flight 030527x1 (2 CDs)
- Raw laser files in ASCII format of each flight.
  - o Flight 030526x1 (2 CDs)
  - o Flight 030527x1 (2 CDs)
- Video MPEGs of each flight's forward, and down imagery.
  - o Flight 030526x1 (4 DVDs, 2 at 45 degrees and 2 at 90 degrees)
  - o Flight 030527x1 (4 DVDs, 2 at 45 degrees and 2 at 90 degrees)
- Firewire Images of each flight's forward, and down view.
  - o Flight 030526x1 (2 DVDs)
  - o Flight 030527x1 (2 DVDs)

### 5.1 GPS COORDINATE ADJUSTMENT SUMMARYS

### 5.1a FREE ADJUSTMENT

### **Network Adjustment Report**

Project: GCMRC\_2003

User name

cel

Date & Time

4:04:11 PM

06/09/2003

Coordinate System US State Plane 1983 Zone

Arizona Central 0202

**Project Datum Vertical Datum**  NAD 1983 (Conus)

Ellipsoidal heights

Geoid Model

GEOID99 (Conus)

**Coordinate Units Distance Units** 

Meters Meters

**Height Units** 

Meters

### **Adjustment Style Settings - 95% Confidence Limits**

### **Residual Tolerances**

**To End Iterations** 

: 0.000010m

Final Convergence Cutoff: 0.005000m

### **Covariance Display**

### Horizontal

Propogated Linear Error [E]: U.S.

Constant Term [C]

: 0.00000000m

Scale on Linear Error [S]

: 1.96

### Three-Dimensional

Propogated Linear Error [E]: U.S.

Constant Term [C]

: 0.00000000m

Scale on Linear Error [S]

: 1.96

### Elevation Errors were used in the calculations.

### **Adjustment Controls**

**Compute Correlations for Geoid**: False

Horizontal and Vertical adjustment performed

### **Set-up Errors**

**GPS** 

Error in Height of Antenna: 0.001m Centering Error: 0.001m

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### **Statistical Summary**

### Successful Adjustment in 1 iteration(s)

Network Reference Factor: 1.03 Chi Square Test (α=95%): PASS Degrees of Freedom: 12.00

### **GPS Observation Statistics**

Reference Factor : 1.03 Redundancy Number (r) : 12.00

### **Individual GPS Observation Statistics**

<b>Observation ID</b>	Reference Factor	Redundancy Number
B2	0.88	2.19
B5	1.29	0.58
B8	0.89	0.91
B9	1.04	1.33
B12	1.24	2.19
B14	0.63	0.66
B16	1.27	2.06
B20	0.66	2.09

B24	1.00	0.00

### **Weighting Strategies**

### **GPS Observations**

**User-defined Scalar Applied to All Observations** 

**Scalar**: 7.04

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### **Adjusted Coordinates**

### Adjustment performed in WGS-84

**Number of Points** 

: 6

**Number of Constrained Points**: 1

. -

### **Adjusted Grid Coordinates**

**Horizontal and Height Only** 

Errors are reported using 1.96σ.

<b>Point Name</b>	Northing	N error	Easting	E error	Elevation	e error	Fix
EMIN	599267.973m	0.000m	221056.274m	0.000m	N/A	N/A	NEh
SCTH	607113.236m	0.006m	212416.689m	0.005m	N/A	N/A	
DSVW	559039.781m	0.008m	221146.265m	0.006m	N/A	N/A	
L404	650702.434m	0.007m	250206.447m	0.005m	N/A	N/A	
BCTH	610746.876m	0.006m	214688.936m	0.004m	N/A	N/A	
FRED	664333.415m	0.018m	161504.365m	0.014m	N/A	N/A	

### **Adjusted Geodetic Coordinates**

### Errors are reported using 1.96σ.

Point Name	Latitude	N error	Longitude	E error	Height	h error	Fix
EMIN	36°24'12.03777"N	0.000m	111°49'51.09660"W	0.000m	1742.567m	0.000m	Lat Long

							h
SCTH	36°28'26.68879"N	0.006m	111°55'37.89583"W	0.005m	1676.303m	0.014m	
DSVW	36°02'26.77444"N	0.008m	111°49'48.92358"W	0.006m	2263.404m	0.017m	
L404	36°51'58.31245"N	0.007m	111°30'12.23482"W	0.005m	1314.374m	0.014m	
ВСТН	36°30'24.58059"N	0.006m	111°54'06.58991"W	0.004m	1611.524m	0.012m	
FRED	36°59'17.97790"N	0.018m	112°29'57.13542"W	0.014m	1530.766m	0.035m	

### **Coordinate Deltas**

Point Name	ΔNorthing	ΔEasting	ΔElevation	ΔHeight	<b>ΔGeoid Separation</b>
EMIN	0.000m	0.000m	N/A	0.000m	N/A
SCTH	0.000m	0.000m	N/A	0.000m	N/A
DSVW	0.000m	0.000m	N/A	0.000m	N/A
L404	0.000m	0.000m	N/A	0.000m	N/A
ВСТН	0.000m	0.000m	N/A	0.000m	N/A
FRED	0.000m	0.000m	N/A	0.000m	N/A

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### **Control Coordinate Comparisons**

Values shown are control coord minus adjusted coord.

Point Name	ΔNorthing	ΔEasting	ΔElevation	ΔHeight
EMIN	N/A	N/A	N/A	N/A
DSVW	-0.004m	0.007m	N/A	-0.006m
L404	-0.003m	0.007m	N/A	0.067m
FRED	-0.002m	0.003m	N/A	-0.021m

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### **Adjusted Observations**

Adjustment performed in WGS-84

**GPS Observations** 

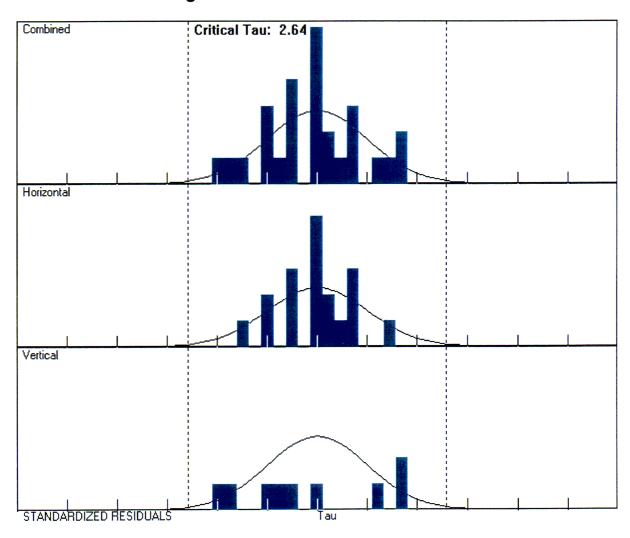
**Number of Observations**: 9 **Number of Outliers**: 0

### Observation Adjustment (Critical Tau = 2.64). Any outliers are in red.

Obs. ID	From Pt.	To Pt.		Observation	A-posteriori Error (1.96σ)	Residual	Stand. Residual
B16	L404	DSVW	Az.	197°50'11.6733"	0°00'00.0170"	0°00'00.0102"	0.80
			ΔHt.	949.030m	0.020m	-0.027m	-1.92
			Dist.	96167.854m	0.009m	0.005m	0.64
B5	EMIN	DSVW	Az.	179°55'21.1170"	0°00'00.0323"	0°00'00.0067"	-0.89
			ΔHt.	520.837m	0.017m	0.009m	1.86
			Dist.	40232.285m	0.008m	0.000m	0.09
B9	EMIN	ВСТН	Az.	331°02'01.9524"	0°00'00.0747"	0°00'00.0038"	0.11
			ΔHt.	-131.043m	0.012m	-0.009m	-1.69
			Dist.	13127.931m	0.005m	-0.001m	-0.41
B12	EMIN	SCTH	Az.	312°17'32.2366"	0°00'00.0936"	0°00'00.0420"	-0.45
			ΔHt.	-66.264m	0.014m	0.016m	1.67
			Dist.	11671.236m	0.005m	-0.007m	-1.49
B2	EMIN	SCTH	Az.	312°17'32.2366"	0°00'00.0936"	0°00'00.0364"	0.61
			ΔHt.	-66.264m	0.014m	-0.018m	-0.57
			Dist.	11671.236m	0.005m	0.005m	1.49
B14	SCTH	ВСТН	Az.	32°00'46.7252"	0°00'00.2120"	0°00'00.0013"	0.02
			ΔHt.	-64.779m	0.010m	0.003m	1.29
			Dist.	4286.038m	0.005m	0.000m	0.19
B8	EMIN	L404	Az.	29°35'37.2965"	0°00'00.0202"	0°00'00.0075"	-1.07
			ΔHt.	-428.193m	0.014m	-0.005m	-0.88
			Dist.	59126.024m	0.006m	-0.001m	-0.45
B20	ВСТН	L404	Az.	41°38'38.0660"	0°00'00.0275"	0°00'00.0145"	0.70
			ΔHt.	-297.150m	0.017m	-0.008m	-0.69

			Dist.	53464.743m	0.007m	0.002m	0.30
B24	EMIN	FRED	Az.	317°35'01.2719"	0°00'00.0385"	0°00'00.0000"	0.00
			ΔHt.	-211.801m	0.035m	0.000m	0.00
			Dist.	88211.948m	0.016m	0.000m	0.00

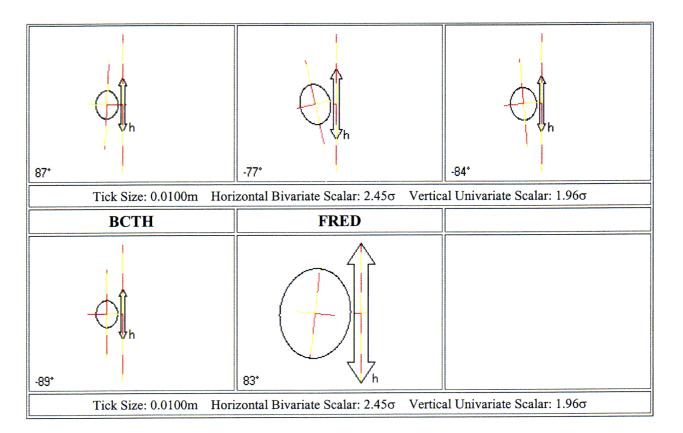
### **Histograms of Standardized Residuals**



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### **Point Error Ellipses**

SCTH	DSVW	L404



### **Covariant Terms**

### Adjustment performed in WGS-84

From Point	To Point		Components	A-posteriori Error (1.96σ)	Horiz. Precision (Ratio)	3D Precision (Ratio)
EMIN	SCTH	Az.	312°17'32.2366"	0°00'00.0936"	1:2293589	1:2293589
		ΔHt.	-66.264m	0.014m		
		ΔElev.	?	?		
		Dist.	11671.236m	0.005m		
EMIN	DSVW	Az.	179°55'21.1170"	0°00'00.0323"	1:4994691	1:4994691
		ΔHt.	520.837m	0.017m		
		ΔElev.	?	?		
		Dist.	40232.285m	0.008m		
EMIN	L404	Az.	29°35'37.2965"	0°00'00.0202"	1:9563459	1:9563459

		ΔHt.	-428.193m	0.014m		
		ΔElev.	?	?		
		Dist.	59126.024m	0.006m		
EMIN	ВСТН	Az.	331°02'01.9524"	0°00'00.0747"	1:2449366	1:2449366
		ΔHt.	-131.043m	0.012m		
		ΔElev.	?	?		
		Dist.	13127.931m	0.005m		
EMIN	FRED	Az.	317°35'01.2719"	0°00'00.0385"	1:5562283	1:5562283
		ΔHt.	-211.801m	0.035m		
		ΔElev.	?	?		
		Dist.	88211.948m	0.016m		
SCTH	ВСТН	Az.	32°00'46.7252"	0°00'00.2120"	1:882848	1:882848
		ΔHt.	-64.779m	0.010m		
		ΔElev.	?	?		
		Dist.	4286.038m	0.005m		
DSVW	L404	Az.	17°38'32.5008"	0°00'00.0168"	1:10534124	1:10534124
		ΔHt.	-949.030m	0.020m		
		ΔElev.	?	?		
		Dist.	96167.854m	0.009m		
L404	ВСТН	Az.	221°52'55.0083"	0°00'00.0276"	1:7423999	1:7423999
		ΔHt.	297.150m	0.017m		
		ΔElev.	?	?		•
		Dist.	53464.743m	0.007m		

# St. Louis District COE / Grand Canyon Monitoring & Research Center

South Canyon & Eminence Sites Grand Canyon, Arizona JCLS Job # 03-6027

## Constrained Adjustment

DESCRIPTION	Temporary Station Set by GCMRC (Future Bluebook)	DESERT VIEW PID AJ5640	EMIN PID AJ5639	L 404 PID GP0283	Temporary Station	FREDONIA CORS L1 PHASE CENTER PID A18806
DELTA GPS METERS		0.009	0.000	-0.064		0.016
PUB. ELLIP METERS		2263,398	1742.567	1314,441		1530.750
ELLIP METERS	1676.303	2263.407	1742.567	1314.377	1611.524	1530.766
POSITION (NAD83)	36 28 26.68880 111 55 37.89581	36 02 26.77433 111 49 48.92330	36 24 12.03777 111 49 51.09660	36 51 58.31235 111 30 12.23455	36 30 24.58059 111 54 06.58988	36 59 17.97802 112 29 57.13539
А	Z	ZB	ZB	z>	z>	ΖŞ
NAME	SCTH	DSVW	EMIN	L404	встн	FRED

vertically. These coordinates were used as control for the FLI-MAP survey performed on May 2003. Reference section 5.1C (communications) for the email Note: The positions of the control stations listed above are referenced to NAD83(2001 FBN Arizona) horizontally & (2001 FBN Arizona) ellipsodal heights containing the 2001 FBN Arizona coordinates provided by Keith Kohl (GCMRC Survey Department). The horizontal positions were computed in a least squares adjustment of the GPS data by holding to the published position of "DSVW", "EMIN", & "L404".

The vertical positions (ellipsoidal heights) were computed in a least squares adjustment of the GPS data by holding to a published ellipsoidal height of

### **5.1b CONSTRAINED ADJUSTMENT**

### **Network Adjustment Report**

Project: GCMRC 2003

User name

cel

Date & Time

4:08:05 PM

06/09/2003

Coordinate System US State Plane 1983 Zone

Arizona Central 0202

**Project Datum** 

NAD 1983 (Conus)

**Vertical Datum** 

Ellipsoidal heights

Geoid Model

GEOID99 (Conus)

**Coordinate Units Distance Units** 

Meters Meters

**Height Units** 

Meters



### **Adjustment Style Settings - 95% Confidence Limits**

### **Residual Tolerances**

**To End Iterations** 

: 0.000010m

Final Convergence Cutoff: 0.005000m

### **Covariance Display**

### Horizontal

Propogated Linear Error [E]: U.S.

Constant Term [C]

: 0.00000000m

Scale on Linear Error [S]

: 1.96

### Three-Dimensional

Propogated Linear Error [E]: U.S.

Constant Term [C]

: 0.00000000m

Scale on Linear Error [S]

: 1.96

### Elevation Errors were used in the calculations.

### **Adjustment Controls**

**Compute Correlations for Geoid**: False

Horizontal and Vertical adjustment performed

### **Set-up Errors**

### **GPS**

**Error in Height of Antenna**: 0.001m **Centering Error**: 0.001m

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### **Statistical Summary**

### Successful Adjustment in 1 iteration(s)

Network Reference Factor: 1.26 Chi Square Test (α=95%): PASS Degrees of Freedom: 14.00

### **GPS Observation Statistics**

Reference Factor : 1.26 Redundancy Number (r) : 14.00

### **Individual GPS Observation Statistics**

<b>Observation ID</b>	Reference Factor	Redundancy Number
B2	0.81	2.19
B5	2.18	1.87
B8	0.95	1.40
В9	1.10	1.34
B12	1.29	2.19
B14	0.66	0.67
B16	1.12	2.15
B20	1.06	2.19

B24    1.00   0.00
--------------------

### **Weighting Strategies**

### **GPS Observations**

**User-defined Scalar Applied to All Observations** 

**Scalar**: 7.04

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### **Adjusted Coordinates**

### Adjustment performed in WGS-84

Number of Points : 6
Number of Constrained Points : 3
Horizontal Only : 2
Horizontal and Height Only : 1

### **Adjusted Grid Coordinates**

Errors are reported using  $1.96\sigma$ .

Point Name	Northing	N error	Easting	E error	Elevation	e error	Fix
EMIN	599267.973m	0.000m	221056.274m	0.000m	N/A	N/A	NEh
SCTH	607113.236m	0.007m	212416.689m	0.006m	N/A	N/A	
DSVW	559039.778m	0.000m	221146.272m	0.000m	N/A	N/A	ΝE
L404	650702.431m	0.000m	250206.453m	0.000m	N/A	N/A	NE
ВСТН	610746.876m	0.007m	214688.937m	0.006m	N/A	N/A	
FRED	664333.418m	0.023m	161504.365m	0.020m	N/A	N/A	

### **Adjusted Geodetic Coordinates**

Errors are reported using 1.96σ.

Point Name	Latitude	N error	Longitude	E error	Height	h error	Fix
EMIN	36°24'12.03777"N	0.000m	111°49'51.09660"W	0.000m	1742.567m	0.000m	Lat

							Long h
SCTH	36°28'26.68879"N	0.007m	111°55'37.89581"W	0.006m	1676.303m	0.017m	
DSVW	36°02'26.77433"N	0.000m	111°49'48.92330"W	0.000m	2263.407m	0.021m	Lat Long
L404	36°51'58.31235"N	0.000m	111°30'12.23455"W	0.000m	1314.377m	0.017m	Lat Long
ВСТН	36°30'24.58059"N	0.007m	111°54'06.58988"W	0.006m	1611.524m	0.015m	
FRED	36°59'17.97802"N	0.023m	112°29'57.13539"W	0.020m	1530.766m	0.043m	

### **Coordinate Deltas**

Point Name	ΔNorthing	ΔEasting	ΔElevation	ΔHeight	ΔGeoid Separation
EMIN	0.000m	0.000m	N/A	0.000m	N/A
SCTH	0.000m	0.000m	N/A	0.000m	N/A
DSVW	0.000m	0.000m	N/A	0.003m	N/A
L404	0.000m	0.000m	N/A	0.003m	N/A
ВСТН	0.000m	0.001m	N/A	0.000m	N/A
FRED	0.004m	0.001m	N/A	0.000m	N/A

### Back to top

### **Control Coordinate Comparisons**

Values shown are control coord minus adjusted coord.

Point Name	ΔNorthing	ΔEasting	ΔElevation	ΔHeight
EMIN	N/A	N/A	N/A	N/A
DSVW	N/A	N/A	N/A	-0.009m
L404	N/A	N/A	N/A	0.064m
FRED	-0.006m	0.002m	N/A	-0.021m

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### **Adjusted Observations**

### Adjustment performed in WGS-84

### **GPS Observations**

GPS Transformation Group: <GPS Default>

**Azimuth Rotation**:  $-0^{\circ}00'00.0070"$  (1.96 $\sigma$ ):  $0^{\circ}00'00.0193"$ 

**Network Scale** : 0.99999998 **(1.96\sigma)** : 0.00000011

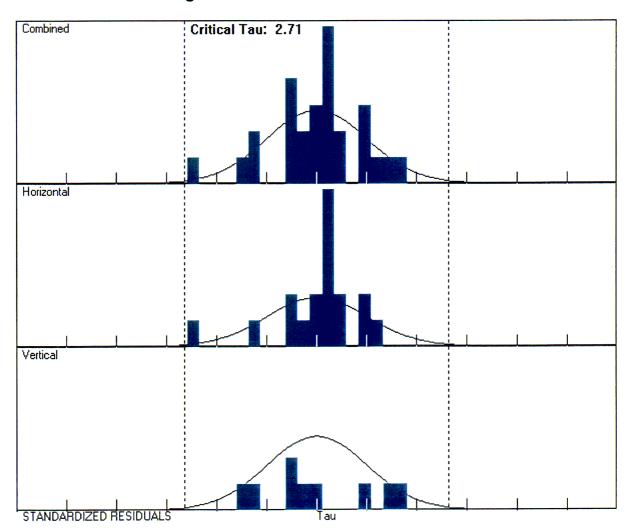
**Number of Observations**: 9 **Number of Outliers**: 0

Observation Adjustment (Critical Tau = 2.71). Any outliers are in red.

Obs. ID	From Pt.	To Pt.		Observation	A-posteriori Error (1.96σ)	Residual	Stand. Residual
B5	EMIN	DSVW	Az.	179°55'21.0737"	0°00'00.0193"	0°00'00.0500"	-2.50
			ΔHt.	520.840m	0.021m	0.012m	1.86
			Dist.	40232.288m	0.004m	0.003m	0.53
B16	L404	DSVW	Az.	197°50'11.6658"	0°00'00.0193"	0°00'00.0027"	0.16
			ΔHt.	949.030m	0.024m	-0.027m	-1.55
			Dist.	96167.852m	0.010m	0.002m	0.27
B12	EMIN	SCTH	Az.	312°17'32.2355"	0°00'00.1150"	0°00'00.0430"	-0.37
			ΔHt.	-66.264m	0.017m	0.016m	1.38
			Dist.	11671.236m	0.006m	-0.007m	-1.31
B9	EMIN	ВСТН	Az.	331°02'01.9559"	0°00'00.0916"	0°00'00.0073"	0.18
			ΔHt.	-131.043m	0.015m	-0.008m	-1.31
			Dist.	13127.930m	0.007m	-0.002m	-0.57
B20	ВСТН	L404	Az.	41°38'38.0846"	0°00'00.0300"	0°00'00.0331"	1.24
			ΔHt.	-297.148m	0.021m	-0.006m	-0.40
			Dist.	53464.744m	0.008m	0.002m	0.27
B2	EMIN	SCTH	Az.	312°17'32.2355"	0°00'00.1150"	0°00'00.0354"	0.48
			ΔHt.	-66.264m	0.017m	-0.018m	-0.46
			Dist.	11671.236m	0.006m	0.005m	1.10

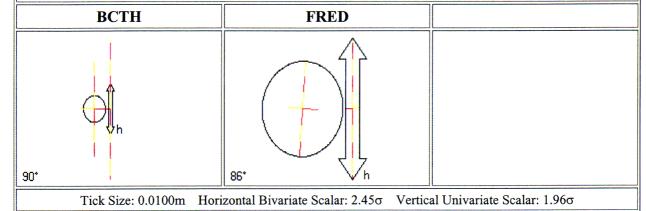
B14	SCTH	ВСТН	Az.	32°00'46.7410"	0°00'00.2603"	0°00'00.0170"	0.21
			ΔHt.	-64.779m	0.012m	0.003m	1.09
			Dist.	4286.038m	0.006m	0.000m	0.13
B8	EMIN	L404	Az.	29°35'37.3160"	0°00'00.0193"	0°00'00.0120"	1.02
			ΔHt.	-428.190m	0.017m	-0.002m	-0.27
			Dist.	59126.023m	0.006m	-0.002m	-0.58
B24	EMIN	FRED	Az.	317°35'01.2719"	0°00'00.0473"	0°00'00.0000"	0.00
			ΔHt.	-211.801m	0.043m	0.000m	0.00
			Dist.	88211.948m	0.019m	0.000m	0.00

### **Histograms of Standardized Residuals**



## SCTH DSVW L404 h of h

Tick Size: 0.0100m Horizontal Bivariate Scalar:  $2.45\sigma$  Vertical Univariate Scalar:  $1.96\sigma$ 



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### **Covariant Terms**

### Adjustment performed in WGS-84

From Point	To Point		Components	A-posteriori Error (1.96σ)	Horiz. Precision (Ratio)	3D Precision (Ratio)
EMIN	SCTH	Az.	312°17'32.2425"	0°00'00.1168"	1:1849000	1:1849000
		ΔHt.	-66.264m	0.017m		
		ΔElev.	?	?		
		Dist.	11671.236m	0.006m		
EMIN	DSVW	Az.	179°55'21.0807"	0°00'00.0000"	1:0	1:0

		ΔHt.	520.840m	0.021m		
		ΔElev.	?	?		
		Dist.	40232.289m	0.000m		
EMIN	L404	Az.	29°35'37.3229"	0°00'00.0000"	1:0	1:0
		ΔHt.	-428.190m	0.017m		
		ΔElev.	?	?		
		Dist.	59126.025m	0.000m		
EMIN	ВСТН	Az.	331°02'01.9629"	0°00'00.0928"	1:2000653	1:2000653
		ΔHt.	-131.043m	0.015m		
		ΔElev.	?	?		
		Dist.	13127.931m	0.007m		
EMIN	FRED	Az.	317°35'01.2789"	0°00'00.0511"	1:4078604	1:4078604
		ΔHt.	-211.801m	0.043m		
		ΔElev.	?	?		
		Dist.	88211.950m	0.022m		
SCTH	BCTH	Az.	32°00'46.7480"	0°00'00.2599"	1:719509	1:719509
		ΔHt.	-64.779m	0.012m		
		ΔElev.	?	?		
		Dist.	4286.039m	0.006m		
DSVW	L404	Az.	17°38'32.5002"	0°00'00.0000"	1:0	1:0
		ΔHt.	-949.030m	0.024m		
		ΔElev.	?	?		
		Dist.	96167.854m	0.000m		
L404	ВСТН	Az.	221°52'55.0341"	0°00'00.0238"	1:8450523	1:8450523
		ΔHt.	297.148m	0.021m		
		ΔElev.	?	?		
		Dist.	53464.745m	0.006m		

#### **5.1c COMMUNICATIONS**

Re FW Survey Control.txt

From: Keith Kohl [kkohl@usgs.gov] Sent: Monday, June 09, 2003 10:30 AM To: Landry, Connie Subject: Re: FW: Survey Control

#### Connie,

The ellipsoidal height that I used for GPS surveys around EMIN is the 2001 FBN survey result of 1742.567 meters in NAD 83(1992). NGS datasheets are not updated unless coordinates change by 5 cm until the 2005 NSRS adjustment

I will not have revised coordinates for the points until the results are run through Pages and Adjust, and the blue booking is completed with the assisstance of the NGS state advisor.

Keith

"Landry, Connie"

<CLandry@jchance.

To:

"'Keith Kohl'" <kkohl@usgs.gov>

com>
"Thibodeaux, Blaine" cc: "'fmgonz@usgs.gov'" <fmgonz@usgs.gov>,

<BThibodeaux@jchance.com>

06/06/2003 11:58AM

Subject: FW: Survey Control

Mark & Keith.

Have you had an opportunity to review the e-mail below? Will you be able to offer any guidance?

----Original Message----

From: Landry, Connie

Sent: Wednesday, June 04, 2003 10:39 AM To: 'Keith Kohl'; 'F. Mark Gonzales' Cc: Thibodeaux, Blaine

Subject: FW: Survey Control

Keith & Mark,

I have given some additional thought to our quandary. I have a question but 1st let me explain our process.

Static surveys are performed prior to or during FLI-MAP data collection for 3 reasons: 1) to proliferate control stations closer to the project area 2) to verify that the existing control coordinate values will be sufficient or "up to date" and 3) to check observed GPS data against published information (when available).

JCLS will perform the network adjustment and end up with a horizontally constrained adjustment (2 or more constraints) and a vertically free Page 1

Re FW Survey Control.txt

adjustment. In the case of this project 3 horizontal constraints (L404, EMIN & DSVW) and 1 vertical constraint (EMIN). EMIN was chosen as the vertical constraint due to the fact that it is closest to the area of interest. Stations L404 & DSVW are utilized as vertical quality control and their respective heights will not be utilized to compute the positions of the 2 newly set stations (SCTH & BCTH) used as control for the FLI-MAP data collection.

Keith - from the information you have already provided we have 2 potential heights for EMIN: 1742.567 2001- FBN Arizona 1742.55 NGS published

I assume one of these heights will be used as the vertical constraint in our adjustment. The difference between these two heights is 0.017m.

Now the question. Which of these two heights is closer to the height (or is the height) utilized for EMIN when controlling survey data collected within the canyon at Eminence and South Canyon? That will be the height we would prefer to utilize.

On another note - all of the data collected during the FLI-MAP mission is archived. If at some point in the future "up to date" coordinates are produced, the FLI-MAP data can be reprocessed - if the magnitude of coordinate change is significant.

Thanks for your patience on this issue.

----Original Message----From: Landry, Connie

Sent: Wednesday, June 04, 2003 10:50 AM To: 'Keith Kohl'

Subject: RE: Survey Control

Keith,

Sorry about the lack of detail. I loaded the baseline between EMIN and FRED into the static adjustment I already had for the project.

I held to the published ellip. height of EMIN (1742.55).

----Original Message----

From: Keith Kohl [mailto:kkohl@usqs.gov] Sent: Tuesday, June 03, 2003 5:40 PM

To: Landry, Connie Subject: RE: Survey Control

Connie.

What was the height value you used at EMIN?

Keith

"Landry, Connie"<CLandry@jchance.
To: "'Keith Kohl'"<kkohl@usgs.gov>com>
cc: "F. Mark Gonzales"<fmgonz@usgs.gov> To: cc:

Subject: RE: Survey Control

06/03/2003 02:57PM

Keith,

I processed the baseline between Fredonia CORS and EMIN. I held to EMIN in Page 2

Re FW Survey Control.txt the free adjustment and computed an ellipsoidal height of 1530.749 on the phase center of the antenna at Fredonia. The published ellipsoidal height for the Fredonia CORS phase center is 1530.745.

----Original Message----

From: Landry, Connie Sent: Monday, June 02, 2003 5:03 PM

To: 'Keith Kohl'

Cc: F. Mark Gonzales; Thibodeaux, Blaine

Subject: RE: Survey Control

Keith,

Thanks for the feedback. The height deltas from September 2001 and February

2002 are very interesting - as they were generated from a free adjustment. Prior to receiving these values - I was concerned that the fbn 2001 delta of 428.126 may have been a result of multiple constraints within that network. Having said that - the same could also be true for the published coordinate deltas.

It never ceases to amaze me that we have grown to the point that we are concerned about a few centimeters.

I do not think that adding the CORS stations at Fredonia and/or Fern Mesa will change the delta height between L404 and EMIN. But I will investigate and forward the results.

----Original Message----

From: Keith Kohl [mailto:kkohl@usgs.gov]

Sent: Monday, June 02, 2003 4:48 PM

To: Landry, Connie Cc: F. Mark Gonzales

Subject: RE: Survey Control

Connie.

Here are some more interesting values. Two surveys were performed in September 2001 and February 2002 that occupied both EMIN and L404. The resulting free adjustment gave the following results.

(18 hours static data) 428.143 delta height EMIN & L404 February, 2002 428.135 delta height EMIN & L404 September, 2001 (18 hours static data)

Since these values were closer to the fbn2001 result of 428.126 rather than the published 428.18 from NGS, I stayed with the unpublished fbn2001 values available from the AZ state land department that were adjusted holding COSA in Scottsdale fixed.

I'm sure you want to move along on the kinematic processing, however, until I can process the recent data with the 4 local CORS stations that were not available during the 1999 and 2001 fbn surveys, I regret that I can't give you centimeter heights. Have you brought into your adjustment CORS stations at Fredonia and Fern Mesa?

Let me know what you decide to do.

Thank you,

Keith

#### Re FW Survey Control.txt

Keith Kohl GCMRC Survey Department (928) 556-7371

"Landry, Connie"<CLandry@jchance.
To: "'Keith Kohl'"<kkohl@usgs.gov>, "F. Mark Gonzales"com><fmgonz@usgs.gov>

"Thibodeaux, Blaine" <BThibodeaux@jchance.com>

cc: 06/02/2003 12:07PM

Subject: RE: Survey Control

Keith & Mark.

Here are some interesting values:

428.126 delta height between EMIN & L404 - 2001-fbn Arizona (values listed below). 428.191 delta height between EMIN & L404 - 2003 JCLS survey (free adjustment). 428.18 delta height between EMIN & L404 - published NGS values.

Which control values for EMIN have been utilized in the past by the GCMRC to constrain control surveys? Which control values will be utilized to QC the 2003 FLI-MAP project? We want to hold to the coordinates that will match the coordinates utilized by the GCMRC.

We will await your guidance!!

----Original Message----

From: Keith Kohl [mailto:kkohl@usgs.gov] Sent: Monday, June 02, 2003 12:57 PM To: F. Mark Gonzales; clandry@jchance.com

Subject: Re: Survey Control

Connie,

In response to your heights for EMIN, Desert View, and L404

L404 was occupied for two seperate FBN surveys. The 1999 fbn with Nevada and Utah gave L404 an ellipsoid height of 1314.375. The 2001 fbn with Arizona resulted in an ellipsoid height of 1314.441 or 6.6 cm higher. NGS still publishes the height at 1314.37 but it appears that the 2001-fbn value may be closer to the true ellipsoid height. The recent static survey was meant to clarify coordinates adjusted between adjoining states.

Values of the 2001- FBN Arizona (February 2001 data collection; July 2001 results by PAGES (NGS GPS processing software) and ADJUST (NGS network adjustment software)

Desert View	36 02	26.77433	111 49 48.92330	2263.398
EMIN	36 24	12.03777	111 49 51.09660	1742.567
1 404	36 51	58.31235	111 30 12,23455	1314.441

Keith Kohl: GCMRC Survey Department (928) 556-7371

F. Mark Gonzales

Keith To:

Kohl/BRD/USGS/DOI@USGS

05/30/2003 03:32

cc:

#### Re FW Survey Control.txt

PM

Subject: Survey Control

---- Forwarded by F. Mark Gonzales/BRD/USGS/DOI on 05/30/2003 03:32 PM

clandry@

"Landry, Connie" <CLandry@jchance. To: jchance.com,"'fmgonz@usgs.gov'" <fmgonz@usgs.gov>com>

cc:

Subject: Survey Control 05/30/2003 01:31PM

Mark.

We utilized the following control station as our constraints for the static survey. EMIN, Desert View & L 404.

<<emin.txt>> <<desert view.txt>> <<L404.txt>>
The ellipsoidal heights are published to 2 decimal places. Do you have access to ellipsoidal heights published to 3 decimal places? If so would you forward those to me?

Thank you in advance. Hope your static survey was successful.

Connie Landry - Supervisor Field Operations John Chance Land Surveys, Inc.

FLI-MAP Division

Phone: 337-268-3294 337-268-3392 Fax: Cell: 337-962-0161

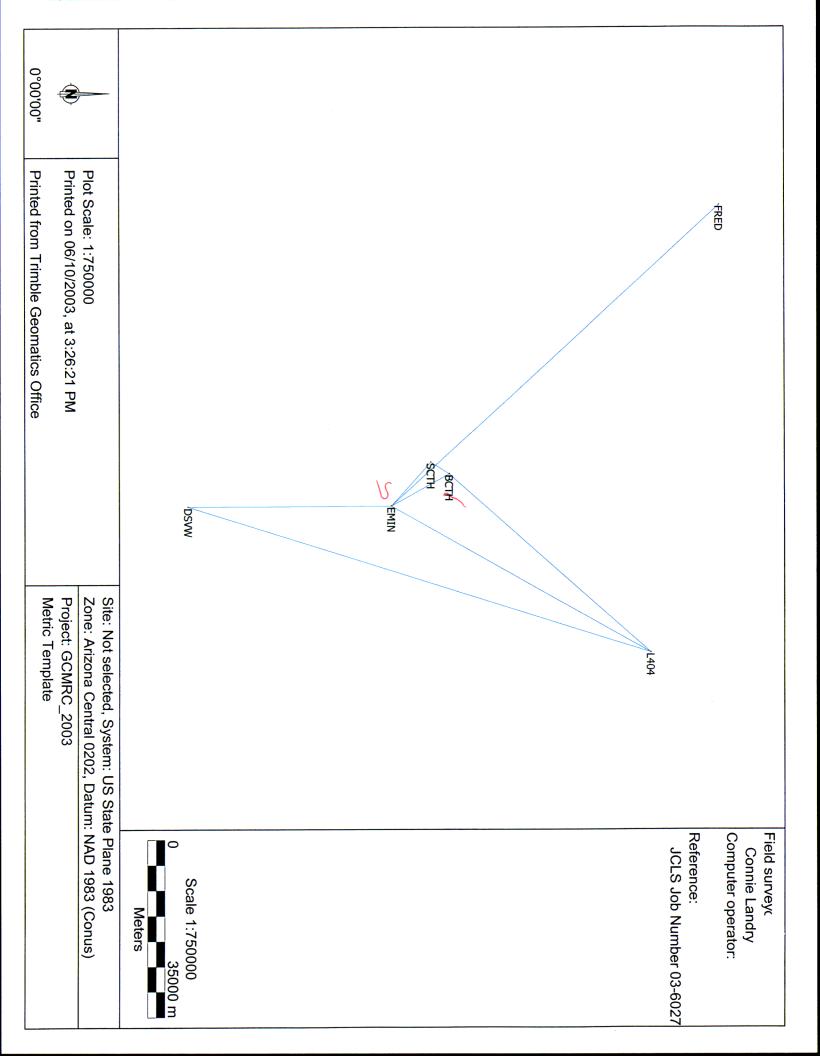
Beeper: 1-800-946-4646 Pin #1440882

E-Mail: clandry@ jchance.com

(See attached file: emin.txt)(See attached file: desert view.txt)(See

attached file: L404.txt)

#### 5.2 SURVEY CONTROL MAPS



#### 5.3 SYSTEM ACCURACY CHECK INFORMATION

# BASE STATION CHECK

# St. Louis District COE / Grand Canyon Monitoring & Research Center South Canyon & Eminence Sites Grand Canyon, Arizona JCLS JOB #03-6027

030526X2	030526X1	FLIGHT
EMIN	ВСТН	NAME
m Z	mΖ	
599267.970 221056.290	610746.870 214688.950	New Mexico Central METERS
1742.550	1611.510	PUB. ELLIP ELEV. METERS
1.398	1.552	TRUE VERT. ANT. HGT METERS
1743.948	1613.062	ANT. ORTHO. HGT. METERS
mΖ	πZ	
599267.93 221056.21	610746.86 214688.98	FLIP7 New Mexico Central METERS
1744	1613.07	FLIP7 ELLIP ELEV. METERS
0.04	0.01	DELTA NORTHING METERS
0.08	-0.03	DELTA EASTING METERS
-0.052	-0.008	DELTA NAVD 88 ELEV. METERS

# BASE STATION CHECK

## St. Louis District COE / Grand Canyon Monitoring & Research Center South Canyon & Eminence Sites Grand Canyon, Arizona JCLS JOB #03-6027

030527X1	FLIGHT
EMIN	NAME
mΖ	
599267.970 221056.290	New Mexico Central METERS
1742.550	PUB. ELLIP ELEV. METERS
1.443	TRUE VERT. ANT. HGT METERS
1743.993	ANT. ORTHO. HGT. METERS
m Z	
599267.96 221056.27	FLIP7 New Mexico Central METERS
1744.02	FLIP7 ELLIP ELEV. METERS
0.01	DELTA NORTHING METERS
0.02	DELTA EASTING METERS
-0.027	DELTA NAVD 88 ELEV. METERS

#### 5.4 ANTENNA HEIGHT INFORMATION SHEETS

CLIENT / PROJECT	AREA: Grand Canyo	n Monitoring and Re	search	
Observer: Chr. 5	Wk/Day: Soup	Ay Date:	Job	
	SESSION 1	SESSION 2	SESSION 3	SESSION 4
Station ID:	BCT H	BCTH		
Julian Date:				
Local Start Time:	10,00	12:05		
Survey Time:	·			
Local Stop Time:	12:00	14:00		<del></del>
	GPS UNIT#_			
SLOPE ANTENNA ME	EASUREMENTS			
Note: All measureme	ents are to be made inside	e notch and bottom edg	ge of ground plane ar	ntenna.
SESSION I	SESSION 2	SESSION	3	SESSION 4
1.647 M 1.649 M 1.651 M	1.635 M 1.636 M 1.638 M		_M _M _M	M M M
<u>5.404</u> FT=N	M <u>6. 570</u> FT=	MFT	=M	FT=M
Mean Slope Distanc	e Mean Slope Dist	ance Mean Slop	_M ne Distance "	Mean Slope Distance
1.647 M 1.649 M 1.651 M	1.635 M 1.636 M 1.638 M		_M _M _M	M M M
5.404 FT= N	M <u>5.370</u> FT=	MFT	=M	FT=M
Mean Slope Distance	Mean Slope Dist	ance Mean Slop	_M ne Distance	Mean Slope Distance
E TRUE VERTICAL  M Vertical Antenna He	L HEIGHT FORMULA M eight Vertical Antenna		0.2334) <sup>2</sup> + 0.0069 _M ntenna Height	M Vertical Antenna Height

CLIENT / PROJECT	AREA: Grand Can	yon Monitoring and	Research	
Observer: <u>FARON</u> O	Wk/Day: <i>SU</i>	Date: 25	7-MAy-03 Job	
	SESSION 1	SESSION 2	SESSION 3	SESSION 4
Station ID:	SCTH	SCT#		
Julian Date:				
Local Start Time:		<u>/2:11</u>		
Survey Time:			l	
Local Stop Time:	12.00	14:00		
	GPS UNIT	r# <u>5</u>		!
SLOPE ANTENNA ME	EASUREMENTS	₹.	A	•
Note: All measureme	ents are to be made insi	ide notch and bottom	edge of ground plane a	antenna.
SESSION 1	SESSION 2	SESSIO	ON 3	SESSION 4
1,648 M 1,648 M 1,649 M	/,642 M /,643 M		M M M	M M M
5,406 FT=/,648	M <u>5,388</u> FT= <u>/.</u>	<u>64</u> 2 <sub>M</sub>	_FT=M	FT=M
/,648 M Mean Slope Distance	<u>//64Z</u> M Mean Slope D	<del></del>	M Slope Distance "	Mean Slope Distance
1,648 M 1,649 M 1,648 M	M M M		M M M	M M M
/,648 M Mean Slope Distance	M	[	M Slope Distance	M Mean Slope Distance
3 TRUE VERTICAL  M Vertical Antenna He	L HEIGHT FORMUL. M eight Vertical Anten	· [	- (0.2334) <sup>2</sup> + 0.0069 M al Antenna Height	9 M Vertical Antenna Height

CLIENT / PROJECT AREA: St. Louis COE/Grand Canyon, AZ					
Observer: 1212-1	Wk/Day:Sunda	y Date:	25-MAY-03	Job03-6027	
	SESSION 1	SESSION 2	SESSION 3	SESSION 4	
Station ID:	DSVW	DSVW		,	
Julian Date:	145	145	145	<del></del>	
Local Start Time:	10:00	12:05	CALL		
Survey Time:					
Local Stop Time:	12:00 /9:02 utc GPS UNIT#_	14:00 Z1:00 UTC	CALL		
SLOPE ANTENNA ME	ASUREMENTS				
Note: All measureme	nts are to be made inside	e notch and bottom ex	ge of ground plane	antenna.	
SESSION 1	SESSION 2	SESSIO	N 3	SESSION 4	
1.561 M 1.562 M 1.562 M	/.5685 M /.5695 M /.568 M		M M M	M M M	
5.123 <sub>FT=1</sub> .561 <sub>M</sub>	5,145 <sub>FT=</sub> 1.56	<u>β</u> MF	T=M	FT=M	
/ S6Z <sub>M</sub> Mean Slope Distance		ance Mean Sle	M ope Distance	Mean Slope Distance	
1.562 M 1.562 M 1.562 M	1.5635 m 1.3695 m 1.568 m		M M M	M M M	
5.123 <sub>FT=1.561<sub>M</sub> 1.562<sub>M</sub> Mean Slope Distance</sub>	1.569 M		T=M  ope Distance	MM Mean Slope Distance	
THE TRUE VERTICAL M  Vertical Antenna He	M		(0.2334) <sup>2</sup> + 0.006 M Antenna Height	9 M Vertical Antenna Height	

CLIENT / PROJECT A	AREA: St. Louis CO	E/Grand Canyon, A	Z	
Observer: CONNIL	Wk/Day:Sund	ay Date:	25-MAY-03Jo	ob03-6027
	SESSION 1	SESSION 2	SESSION 3	SESSION 4
Station ID:	EMIN	EMIN		
Julian Date:	145	145	145	
Local Start Time:	09.58 	12, 03 <del>12:05</del>	CALL	
Survey Time:	2:07 0.00			
Local Stop Time:	12:00	14:00	CALL	<del></del> .
	GPS UNIT			
SLOPE ANTENNA ME	EASUREMENTS			
Note: All measureme	ents are to be made inside	de notch and bottom ed	dge of ground plane a	ntenna.
SESSION 1	SESSION 2	SESSIO	N 3	SESSION 4
1.515 M 1.515 M 1.515 M 4.515 M	1,368 M 1,3695 M 1,369 M 4,497 4, FT=	371 MF	M M M T=M	M M FT=M
/ 515 M Mean Slope Distance	1,369 M		M ope Distance	Mean Slope Distance
$\frac{1.515}{1.516}M$ $\frac{1.516}{1.514}M$ $\frac{470}{FT} = \frac{515}{1.5}M$ Mean Slope Distance	MFT= M	MF	MMM T=MM ope Distance	MMFT=MMM Mean Slope Distance
THE TRUE VERTICA M  Vertical Antenna H	L HEIGHT FORMULA	$A = \sqrt{(Mean SD)^2} -$	•	-

CLIENT / PROJECT A	REA: St. Louis CC	E/Grand Canyon,	, <b>AZ</b>	
Observer: BLAQNE 7.	Wk/Day:Sund	ay Date:_	25-MAY-03_	_Job03-6027
	SESSION 1	SESSION 2	SESSION 3	SESSION 4
Station ID:	L404	L404		,
Julian Date:	145	145	145	
Local Start	10:00	12:05	CALL	
Survey Time:				
Local Stop Time:	12:00	14:00	CALL	
	GPS UNIT#	<u></u>		
SLOPE ANTENNA MEA	ASUREMENTS			
Note: All measuremen	ts are to be made insid	le notch and bottom	edge of ground plane	antenna.
SESSION 1	SESSION 2	SESSI	ON 3	SESSION 4
1.480 M 1.478 M	<u>1.422                                   </u>		M M M	M M M
<u>4.848</u> ft= <u>],498</u> m	4.66 FT= 1.4	<u></u> M	_FT=M	FT=M
1.479 M Mean Slope Distance	/.42/ M Mean Slope Dis	stance Mean	M Slope Distance	Mean Slope Distance
<u>1.480</u> м <u>1.480</u> м <u>1.478</u> м	1,422 <sub>M</sub> 1.421 M 1,419 M		M M M	M M M
FT= 1.478M	4.60 FT=11	<u></u>	_FT=M	FT=M
<u>/. 479</u> M Mean Slope Distance	<u>  42   M</u> Mean Slope Di	stance Mean	M Slope Distance	Mean Slope Distance
THE TRUE VERTICAL	<u>1.408</u> м		- (0.2334) <sup>2</sup> + 0.000 M ral Antenna Height	69  M  Vertical Antenna Height

09:45 13:10	JOHN CHANCE LA FLI-MAP GPS	AND SURVEYS, INC.  S DATA SHEET  AMADDING	X10:06 HELICOPTER LATED FROM
	CORRIDO	KMAIIMO 7/2.5	7 HELICOPTER LIFTED FROM
CLIENT / PROJECT A	AREA: Grand Canyon Monito	oring and Research	THE WITTE LIMBER
Observer: FARON C	Wk/Day: Monoay	Date: <u>Z 6 - MAy - 03</u> Job	
	SESSION 1 SESSIO	N 2 SESSION 3	SESSION 4
Station ID:	SCTH SCTI	<del>/</del>	,
Julian Date:	146 14	12:38	· 
Local Start Time:	09:45 09:53 13:00	CALL	
Survey Time:			
Local Stop Time:	CATUI:44 CAR	<u> 14:30</u>	
	GPS UNIT#		
SLOPE ANTENNA ME	ASUREMENTS		
Note: All measureme	ents are to be made inside notch an	d bottom edge of ground plane	e antenna.
SESSION 1	SESSION 2	SESSION 3	SESSION 4
1,509 M 1,509 M 1,507 M	/.500 M /.500 M /.503 M	M M M	M M M
	M 4,93/ FT= <u>1,503</u> M	M	FT=M
M Mean Slope Distance	e Mean Slope Distance	Mean Slope Distance "	M Mean Slope Distance
	/, 500 M /, 502 M /, 503 M	M M	M M M
4,949 FT= 1,508 N	, <del>,</del>	FT=M	FT=M
M Mean Slope Distance	e Mean Slope Distance	Mean Slope Distance	Mean Slope Distance
7 TRUE VERTICAL	L HEIGHT FORMULA = $\sqrt{MeG}$	$\frac{(0.2334)^2}{(0.2334)^2} + 0.00$	69 M
Vertical Antenna He	ight Vertical Antenna Height	Vertical Antenna Height	Vertical Antenna Height

CLIENT / PROJEC	CT AREA:	St. Louis COE	/Grand Canyon,	\Z			
Observer:C	ONNIE	Wk/Day:	MONDAY	_Date:	26-May-03	_Job #:	03-6027
	SESSI	ION 1	SESSION 2		SESSION 3		SESSION 4
Station ID:	EM	IIN	EMIN			<u>-</u>	
Julian Date:	14		146		146 urc	-	146
Local Start Time:	9:45	16:45	CALL /			-	
Survey Time:	<u> </u>	UTC	urc		urc	-	UTC
Local Stop Time:	13:00		CALL /			_	
		GPS	UNIT#		•		
SLOPE ANTENNA	MEASURE	MENTS					
Note: All measure	ments are to	be made inside	notch and bottom	edge of g	ground plane antenr	ıa.	
SESSION 1		SESSION 2		SESSI	ON 3		SESSION 4
1.486 M 1.487 M 1.488 M	S	1.410 M 1.410 M 1.412 M	u. N		M M M		M M M
4,981 <sub>FT=</sub> 1,41	M	FT=   .	<u>* '</u> M		_FT=M		FT=M
, 487 Mean Slope Distan	ce	Mean Slope Dis	tance	Mean	M Slope Distance		Mean Slope Distance
1.466 M 1.465 M 1.467M	3 <b>5</b>	410 M   412 M   409 M	. 11		M M M		M M M
4. FT= 1.4 1.40 15	M	4. FT= 1.	<u>*''</u> M		_FT=M M		FT=M M
Mean Slope Distan	ace	Mean Slope Dis	stance	Mean	Slope Distance		Mean Slope Distance
THE TRUE VERTI	CAL HEIG	HT FORMULA	$\Lambda = \sqrt{(Mean)}$	$(SD)^2 - (0)^2$	$0.2334)^2 + 0.0069$		
Vertical Antenna I	<b>Height</b>	Vertical Antenn	a Height	Vertic	M al Antenna Height		M Vertical Antenna Height

O9:45	1/3:10
1. /	الم.
13:00	14,26

13:00 14126	CORRIDOR MAPPING						
CLIENT / PROJECT A	REA: Grand Canyon M	Monitoring and Rese	arch				
Observer: Chrus G	Wk/Day: Monday	Date: <u>26 - Ma</u>	,-03 Job				
	SESSION 1 S	ESSION 2	SESSION 3	SESSION 4			
Station ID:	BCTH B	BCTH_					
Julian Date:	140_	140 12:25		-			
Local Start	09:45	-CALL					
Survey Time:		14:35					
	CALL E	ALL					
,	GPS UNIT#						
SLOPE ANTENNA MEA	ASUREMENTS						
Vote: All measuremen	its are to be made inside no	otch and bottom edge	of ground plane	antenna.			
SESSION 1	SESSION 2	SESSION 3		SESSION 4			
1.561 M 1.563 M 1.564 M	1.570 M 1.57 M 1.57 Z M		M M M	M M M			
5./30 FT=1.544 M	5.151 FT= 1.570 ]	MFT=	M	FT=M			
Mean Slope Distance	Mean Slope Distance		M Distance	Mean Slope Distance			
1.563 M 1.563 M 1.564 M	0570 M   0571 M   0572 M		M M M	M M M			
5.130 FT=1.564 M	SolSI FT= 10570	MFT=	M	FT=M			
1.563 M Mean Slope Distance	1.57/ M Mean Slope Distance		M Distance	Mean Slope Distance			
TRUE VERTICAL	HEIGHT FORMULA =	$\sqrt{(Mean SD)^2 - (0)}$	$\frac{1}{(2334)^2} + 0.006$	9			
I.55Z M Vertical Antenna Hei	<u>  1.560 M</u> ght Vertical Antenna H		_M tenna Height	M Vertical Antenna Height			

CLIENT / PROJECT A	AREA: Grand Canyon Mo	nitoring and Research	
Observer: Chris	Wk/Day: Tuesday	Date: <u>05.27.03</u> Job	)
a de la companya de	SESSION 1 SES	SSION 2 SESSIO	N 3 SESSION 4
Station ID:	BCTH B	<u>-TH</u>	,
Julian Date:	1471	47	
Local Start Time:			
Survey Time:			
Local Stop Time:		·	<del></del>
	GPS UNIT##	7	
SLOPE ANTENNA ME	ASUREMENTS		
Note: All measureme	ents are to be made inside note	h and bottom edge of ground p	olane antenna.
SESSION 1	SESSION 2	SESSION 3	SESSION 4
1.510 M 1.509 M 1.510 M	M M M	M M M	M M M
4.955 FT= 1.510 M	FT=M	FT=M	FT=M
SIO M Mean Slope Distance	Mean Slope Distance	Mean Slope Distance	Mean Slope Distance
18510 M 1809 M 1810 M	M M M	M M M	M M M
4.955 FT= 6510 N	FT=M	FT=M	FT=M
<u>l⊳Sl⊘</u> M Mean Slope Distance	Mean Slope Distance	Mean Slope Distance	Mean Slope Distance
3 TRUE VERTICAL  1.499 M  Vertical Antenna He	M	$Mean SD)^2 - (0.2334)^2 + 0$ M  Vertical Antenna Height	M

#### 11:00 12:28

## JOHN CHANCE LAND SURVEYS, INC. \*HELICOPTER LIFTED FLI-MAP GPS DATA SHEET CORRIDOR MAPPING

CLIENT / PROJECT A	REA: Grand Canyo	on Monitoring and I	Research	
Observer: FARON O	)Wk/Day:_ <i>/UESD</i>	Date: <u>27-</u>	<u>Мау-03</u> Job	
	SESSION 1	SESSION 2	SESSION 3	SESSION 4
Station ID:	SCT4	SCTH		
Julian Date:	147			
Local Start Time:	10:30 09:41			
Survey Time:				
Local Stop Time:	12:28			<del></del>
	GPS UNIT#_			
SLOPE ANTENNA MEA	ASUREMENTS			
Note: All measuremen	nts are to be made inside	e notch and bottom e	edge of ground plane a	untenna.
SESSION 1	SESSION 2	SESSIO	N 3	SESSION 4
1,587 1,587 M 1,586 M	M M		M M M	M M M
5.205 FT=1,586M	FT=	M]	FT=M	FT=M
1.5866 M Mean Slope Distance	Mean Slope Dis	tance Mean S	M lope Distance "	M Mean Slope Distance
/, 587 /, 587 M /, 586 M	M M M	1	M M M	M M M
5.205 FT= $/.580$ M	FT=	M	FT=M	FT=M
M Mean Slope Distance	Mean Slope Dis	tance Mean S	M lope Distance	Mean Slope Distance
E TRUE VERTICAL	, HEIGHT FORMULA M ight Vertical Antenn		- (0.2334) <sup>2</sup> + 0.006 M l Antenna Height	9 M Vertical Antenna Height

CLIENT / PROJE	ECT AREA:	St. Louis COF	C/Grand Canyon,	AZ			
bserver:	CONNIE	Wk/Day:	TUESDAY	Date: _	27-May-03	_Job #:	03-6027
	SESS	SION 1	SESSION 2		SESSION 3		SESSION 4
tation ID:		MIN 47	<u>EMIN</u> 147		147	_	147
ılian Date:		46-	UTC		-146- UTC		146- UTC
scal Start Time:	10:30	-/ 17:30	CALL /			<b>-</b>	
urvey Time:		UTC	итс		итс	_	итс
ocal Stop Time:	12:30	/ 19:30	CALL /	<del></del> -		_	
			UNIT#		· · · · · · · · · · · · · · · · · · ·		
LOPE ANTENNA	A MEASURE	MENTS					
Note: All measur	rements are to	o be made inside	notch and bottom	edge of gr	ound plane anten	na.	
SESSION 1		SESSION 2		SESSIO	N 3		SESSION 4
1.455 M		M M			M M		M M
1, 456M	55	M			M		M
1.455 <sub>M</sub>	_M	FT=	M	I	?T=M		FT=M
Mean Slope Dista	ance	M Mean Slope Dis	tance	Mean Si	M lope Distance		Mean Slope Distance
M M		M M			M M		M M
M FT=	M	M FT=	M		M FT=M		M FT=M
F1	IVI	F1	IVI		M		rıw
Mean Slope Dista	ance	Mean Slope Dis	tance	Mean Si	lope Distance		Mean Slope Distance
HE TRUE VERT	ICAL HEIG	HT FORMULA	$\Lambda = \sqrt{(Mean)}$	$(SD)^2 - (0.5)$	$2334)^2 + 0.0069$		
Vertical Antenna	Height	M Vertical Antenna	a Height	Vertical	M Antenna Height		M Vertical Antenna Height

#### 5.5 FLIGHT LOG INFORMATION SHEETS

					4	30 N	ઉં ઉ	EE																		
	SCHAR	1/38950		S Browsand	Yorgen Recd	7	अनुसन्धः (११८)		9		्रत्य असीक्ष्मक्ष	5 50	The second secon			8		1,30	31	5,16						
	CLIENT	TAIL NUMBER $ \mathcal{L} $		OPERATOR	OBSERVER	100 m	Web administrative		00/			HD 28 H	Mesez	₩ 39	(Os.)5	24	<b>)</b>	1814	18:36	18, 36						•
	03-6017	130526×1		alter 11:08er	HAIL MARKS SECTION BLAKEN	5 4	HARRY SECONDARY	1 3 3 0 3 2 3	Ø 2 3 0 1 2 3	@	IVS) BOX ( PERINTARY	9 OF 9	SAKING SEE	8 JO	なるな	22,2		h8:10:11	17:30:29	17: 33; 24	Mary of State in Mary Lawrence and the state	28°C 32.4°F	Calm	clear		
A Transport	JOB NUMBER	FLIGHT NUMBER	ा.हर्स्	M LOTI	THE SECTION OF	N/S	Ser (INGS	GAIN 0	THRESHOLD 0	SCAN ANGLE 30	SATO) TY. (C) E	DISK# DF	and the second second second second	DISK#	±lΩla-	HOBBS (hrs)	SYSTEM (hrs)	SURVEY (UTC)	VIDEO (UTC)	LASER (UTC)	WEARTHAN CONDITIONS	TEMP (F)	WIND (kts)	SKY	RETURNE	

	STOP																								START
⊕ા≰⊝)≓⊭ા	START																								stop
	STOP7. 23:40	17:24:41	17:25:55	17,27,11	17. 39:09	17:47:32	17,59,56	18:08:59	18:17:08	18:35:51	PC, R.S. 129	18.33,37	18:34/52	36.1										•	START
शहरूआहलोर?	UK: 88: 61	12.46.71	12	17:26:43	17: 33:38	17,42.37	17:52:28	18:02.58	0 :	18:11:23	18:32:05	14: 32:77		18.35.56											
	LASER	357#	2/6	100	SC1+	-625/	563-	-475 rales	Extof <5.C5-		10/c	サミル	, , , , , , , , , , , , , , , , , , ,	7 1 2 2 2	· · · · · ·	.1		1	<del></del>	•	•	•	<del>*************************************</del>		VIDEO STOP

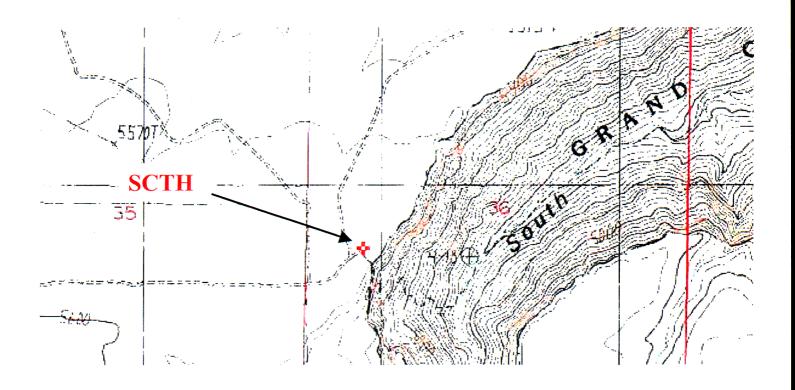
CLIENT GCMARR	OPERATOR STONEARY	At Probable (n) SEER (n)		увас нявичная (м. н. уж.) но 30 г. урбс»	нь <i>39</i> — — — — — — — — — — — — — — — — — — —	21:28:07	21,23;07			
JOB NUMBER 03-6037	11/2	Nis Nis	LE 30 69	STORYGE INS BOX PRIVARY  DISK# DF \( \text{P} \) \( \text{DF} \) \( \text{SP}		SYSTEM (hrs) SURVEY (UTC)   9', 58,34	VIDEO (UTC) $A\mathbf{G}$ , $10.52$ LASER (UTC) $20$ , $13$ , $05$ VIEAVECER (SOND) FFONS	TEMP (F) $\mathcal{A}$ $\mathcal{C}$ WIND (KIS) $\mathcal{E} - \mathcal{S} - / \mathcal{D}$	SKY C BOL	

	STOP																							START
(Sign) ne	START							-3 cc			€ 7.6PS													STOP
	5, C1, 52, 36	$\sim$	01:51:05	20:17:05	_	33 / 3	11:84:08	20:5/1:00	20:59:31	21:07:56	C1.11.11C	1:19:	21:30:48	PH: 18 1149	21:23:07								•	START
الكالفات المالية المالية	IARTO: 12:05	30:13:30	1	40:16:24	100	11.86.00	1 '	, `	1 '	1	n	7	21.30.11	21.21.28	1.22.3	ł								STOP
	LASER	EWIN Y	1000	Noo!	<del>'</del>	EM1-	- CX2	F43-	ニカガヨ	EXM5-	70M-	111111111111111111111111111111111111111	ブジジ		LAGS A	<u> </u>	<del>. !</del>	, <del>1</del> .	· .		•			VIDEO STOP

7,17	10/2/2	EME	001	~-1	<u></u>				151		ή 5.		7	18												
	St. Louis COE	N3895D		S. Broussard	Mike Leshetski	4	SPEED (ms)	(			FREWIRE 14.2	но <b>008</b>			80	300		9:40	3:/3	2,34						
	CLIENT	TAIL NUMBER		OPERATOR	OBSERVER	FFAME	ALTITUDE (m)		100		16396	900 an	MPEG2	원 001	8108			2161	6.Pl	19:2						
	03-6027	030527x1		Walter Wieser	PREMARY SECONDARY	5 4	PREMARY SECONDARY	1 2 3 0 0 2 3	1 2 3 0 1 2 3	(69) oc (69) oc	INS BOX PRIMARY	10 or 1	SECONDARY	DF 2	START	0027.1		19:59:60	18:09:41	ha.11:81	ITIONS	7,78	Light Hariable	Clear		
Ì	JOB NUMBER	FLIGHT NUMBER	CREW	PILOT	SYSTEM	N/S	SETTINGS	GAIN 0	THRESHOLD 0	SCAN ANGLE 3	STORAGE	DISK# DF		DISK#	TIME	HOBBS (hrs)	SYSTEM (hrs)	SURVEY (UTC)	VIDEO (UTC)	LASER (UTC)	WEATHER CONDITIONS	TEMP (F)	WIND (kts)	SKY	REMARKS	

	PROJECT#		FLIGHT#	
LASER	188: 11:64	11.37	START	STOP
\$\$ \frac{1}{2}	18:12:67	18:12:31		
EMEN,	1	18:13:50		
Woo	18:14:30			
-5M2	18:00:31	18:25:11		
EM3-	18:28:17	18:34:12		
EH3-	18:37:10	18:43:15		
FUNT	18:46:06	18:5/18		
EMS-	18,54,38	0		
150M	19:03:26	19:07:44	P-6371	5-6272
<del>/</del>	19:10:33	19:13:14		5-6371
- 11 - 11 - 11 - 11 - 11 - 11 - 11 - 1		04:81:61		
1.75% A	19.19.31	19:19:54		
101	5h:0016)	19:21:17		
~ × × 8 × ×	19:22:05	17,32,34		
1				
				•
<u>.</u>				
VIDEO STOP		START	зтор	START

#### 5.6 CONTROL DESCRIPTION SHEETS



STATION NAME: "SCTH" JCLS IDENTIFIER: "SCTH"

Monument Location: To reach "SCTH" from the Marble Canyon Lodge in Marble Canyon, AZ, travel westerly on Hwy 89A for approx 21.4 miles to a gravel road to the left leading to the House Rock Wildlife Area. Turn left and precede southerly on main road for approx. 18.9 miles to a gravel road on the left (632) leading to the Wildlife Area Headquarters. Turn left and precede ENE for approx. 1.9 miles to a gravel trail on the right leading to South Canyon Trail. Turn right and precede easterly for approx. 1.1 miles to a barbed wire gate. Pass through gate and precede straight approx. 0.1 miles to a parking area. The station is approx. 275 feet east of parking area on the second rim of the canyon. The station is a bolt with punch mark in the middle.

Monument Description: Bolt

**Date:** May 2003

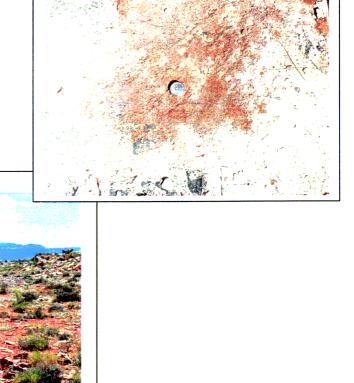
Monument Established By: Grand Canyon Monitoring & Research

#### Adjusted NAD 83 (2001 FBN Arizona) Geodetic Position

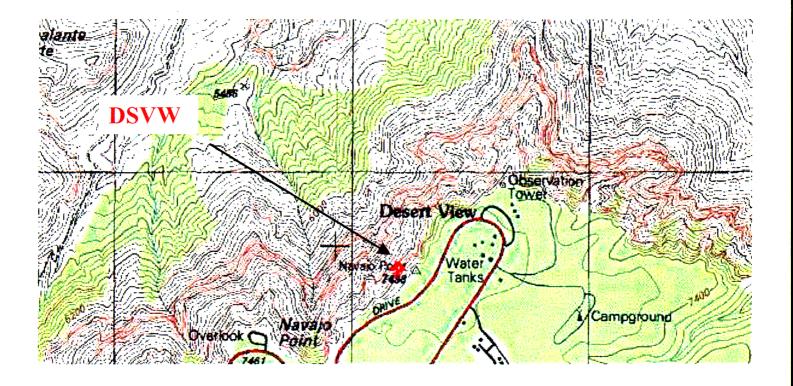
Lat. 36 28 26.68879 N Long. 111 55 37.89581 W

#### Adjusted ELLIP Height(2001 FBN Arizona)

Elevation = 1676.303 m



PAGE 9



STATION NAME: "DESERT VIEW"

PID: "AJ5640"
JCLS IDENTIFIER: "DSVW"

Monument Location: To reach the station from Flagstaff, AZ drive north on US Hwy 89 to the town of Cameron. Turn west (left) on to State Hwy 64 and proceed for 33 miles to the entrance of the Grand Canyon National Park. Continue for 3.7 miles to a pullout on the right and park in the pullout. The pullout is also 0.6 miles beyond the fee station and 0.2 miles west of the west drive of the Desert View Parking lot. The pullout is also 1.7 miles northeasterly on Hwy 64 from the LIPAN View turnoff road. Once you park in the pullout, walk northerly toward the canyon rim for approximately 250 feet to the station. The station is set in top of a 5 inch X 12 inch high concrete pedestal.

Monument Description: Brass disk stamped "DSVW GCMRC 01""

**Date:** May 2003

Monument Established By: GRANCN

#### Published NAD 83 (2001 FBN Arizona) Geodetic Position

Lat. 36 02 26.77433 N Long. 111 49 48.92330 W

#### Published ELLIP Height (2001 FBN Arizona)

Height = 2263.398 m

#### Adjusted NAD 83 (2001 FBN Arizona) Geodetic Position

Lat. 36 02 26.77433N Long. 111 49 48.92330 W

#### Adjusted ELLIP Height (2001 FBN Arizona)

Elevation = 2263.407 m





National Geodetic Survey, Retrieval Date = JUNE 5, 2003

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

DESIGNATION - DESERT VIEW = "DSVW"

PID - AJ5640

STATE/COUNTY- AZ/COCONINO

USGS QUAD - DESERT VIEW (1988)

#### \*CURRENT SURVEY CONTROL

NAD 83(1992)-	36 02 26.77434	(N) 111	49 48.92270	(W)	ADJUSTED
NAVD 88 -	2286.6	(meters)	7502.	(feet)	GPS OBS
<u>x</u> -	-1,920,709.725	(meters)	-th-	·	COMP
Υ -	-4,794,772.204	(meters)			COMP
z -	3,733,182.314	(meters)			COMP
LAPLACE CORR-	3.01	(seconds)			DEFLEC99
ELLIP HEIGHT-	2263.38	(meters)	(10	/04/01)	GPS OBS
GEOID HEIGHT-	-23.21	(meters)			GEOID99
HODY ODDED -	7\				

HORZ ORDER - A
ELLP ORDER - THIRD CLASS II

The horizontal coordinates were established by GPS observations and adjusted by the National Geodetic Survey in October 2001.

The orthometric height was determined by GPS observations and a high-resolution geoid model.

Photographs are available for this station.

The X, Y, and Z were computed from the position and the ellipsoidal ht.

The Laplace correction was computed from DEFLEC99 derived deflections.

The ellipsoidal height was determined by GPS observations and is referenced to NAD 83.

The geoid height was determined by GEOID99.

North East Units Scale Converg.

SPC AZ C - 559,039.778 221,146.287 MT 0.99990075 +0 03 03.0

UTM 12 - 3,988,789.369 425,208.696 MT 0.99966892 -0 29 18.6

U.S. NATIONAL GRID SPATIAL ADDRESS: 12SVE2520988789 (NAD 83)

MARKER: DD = SURVEY DISK

SETTING: 7 = SET IN TOP OF CONCRETE MONUMENT

STAMPING: DSVW GCMRC 01

MAGNETIC: N = NO MAGNETIC MATERIAL

STABILITY: C = MAY HOLD, BUT OF TYPE COMMONLY SUBJECT TO

STABILITY: SURFACE MOTION

SATELLITE: THE SITE LOCATION WAS REPORTED AS SUITABLE FOR SATELLITE: SATELLITE OBSERVATIONS - February 05, 2001

HISTORY - Date Condition Report By
HISTORY - 20010205 MONUMENTED GRANCN
HISTORY - 2003 GOOD JCLS

#### STATION DESCRIPTION

DESCRIBED BY GRAND CANYON MONITORING AND RESEARCH 2001 (FMG)
THIS STATION IS A REPLACEMENT FOR NAVAJO POINT (GP0594) THAT WAS LOST TO
VANDALISM EARLIER THIS YEAR. THE STATION IS LOCATED NEAR DESERT VIEW OVERLOOK
(WATCH TOWER) ON SOUTH RIM DRIVE, HIGHWAY 64, GRAND CANYON, ARIZONA. THE
STATION IS 34 MILES WEST OF CAMERON, AZ, 80 MILES NORTH OF FLAGSTAFF, AZ, AND 55
MILES NORTH OF WILLIAMS, AZ. THE STATION IS NEAR THE EASTERN EDGE OF GRAND
CANYON NATIONAL PARK.

TO REACH THE STATION FROM FLAGSTAFF, AZ DRIVE NORTH ON US HIGHWAY 89 TO THE TOWN OF CAMERON. TURN WEST (LEFT) ON TO STATE HIGHWAY 64 AND PROCEED FOR 33 MILES TO THE ENTRANCE GRAND CANYON NATIONAL PARK. CONTINUE FOR 3.7 MILES TO A PULLOUT ON THE RIGHT (NORTH) AND PARK IN THE PULLOUT. THE PULLOUT IS ALSO O.6 MILES BEYOND THE FEE STATION AND 0.2 MILES FROM WEST DRIVE OF DESERT VIEW PARKING LOT. WALK NORTHERLY TOWARD THE CANYON RIM FOR APPROXIMATELY 250 FT TO THE STATION.

THE STATION IS A 5 INCH X 5 INCH X 12 INCH HIGH CONCRETE PEDESTAL WITH A FLAT BRASS DISK IN THE CENTER APPROXIMATELY 25 FT FROM THE RIM OF THE CANYON. THE STATION DISK IS 2.5 INCHES IN DIAMETER, WITH STAMPINGS DSVW, GCMRC, AND 01.

#### National Geodetic Survey, Retrieval Date = JUNE 5, 2003 \*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

"EMIN"

DESIGNATION - EMIN

- AJ5639 STATE/COUNTY- AZ/COCONINO

USGS QUAD - TATAHATSO POINT (1988)

#### \*CURRENT SURVEY CONTROL

NAD 83(1992)-	36 24 12.03780	(N) 111	49 51.09594	(W)	ADJUSTED
NAVD 88 -	1765.4	(meters)	5792.	(feet)	GPS OBS
X -	-1,911,760.478	(meters)			COMP
Y -	-4,772,286.049	•			COMP
Z -	3,765,341.401	(meters)			COMP
LAPLACE CORR-	2.19	(seconds)			DEFLEC99
ELLIP HEIGHT-	1742.55	(meters)	(10	)/04/01)	GPS OBS
GEOID HEIGHT-	-22.80	(meters)			GEOID99
HORZ ORDER -	A				

ELLP ORDER - THIRD CLASS II

The horizontal coordinates were established by GPS observations and adjusted by the National Geodetic Survey in October 2001.

The orthometric height was determined by GPS observations and a high-resolution geoid model.

The X, Y, and Z were computed from the position and the ellipsoidal ht.

The Laplace correction was computed from DEFLEC99 derived deflections.

The ellipsoidal height was determined by GPS observations and is referenced to NAD 83.

The geoid height was determined by GEOID99.

```
East Units Scale Converg.
                         North
SPC AZ C - 599,267.974 221,056.290 MT 0.99990073 +0 03 03.3
UTM 12 - 4,029,007.280 425,498.962 MT 0.99966838 -0 29 35.2
```

U.S. NATIONAL GRID SPATIAL ADDRESS: 12SVF2549929007 (NAD 83)

MARKER: A = ALUMINUM MARKER

SETTING: 0 = UNSPECIFIED SETTING

STAMPING: EMIN GCMRC 01

MAGNETIC: I = MARKER IS A STEEL ROD

STABILITY: D = MARK OF QUESTIONABLE OR UNKNOWN STABILITY SATELLITE: THE SITE LOCATION WAS REPORTED AS SUITABLE FOR

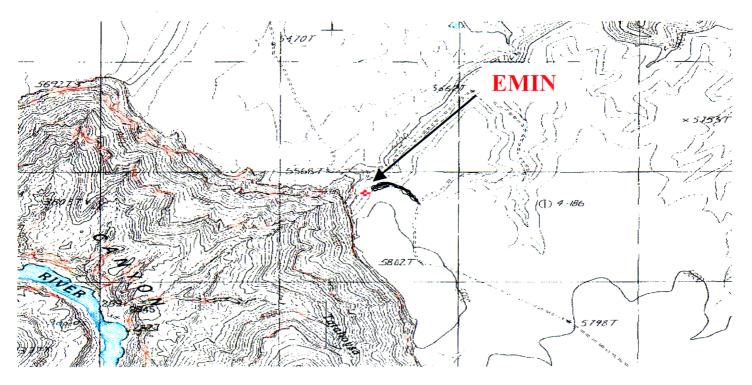
SATELLITE: SATELLITE OBSERVATIONS - April 26, 2001

HISTORY	-	Date	Condition	Report	Ву
HISTORY	_	20010205	MONUMENTED	GRANCN	
HISTORY	-	20010426	SEE DESCRIPTION	GRANCN	
HISTORY	_	2003	GOOD	JCLS	

#### STATION DESCRIPTION

DESCRIBED BY GRAND CANYON MONITORING AND RESEARCH 2001 (FMG)
THE STATION IS LOCATED AT EMINENCE BREAK TRAILHEAD, 40 FT. DUE SOUTH OF A LARGE
4 FT CAIRN MARKING THE TRAILHEAD. TRAILHEAD IS APPROX. 500 FT SOUTHEAST OF
LARGE NOTCH IN KAIBAB LIMESTONE DRAINAGE AND APPROX. 150 FT. HIGHER THAN
ENTRANCE TO DRAINAGE. IT IS A 2.5 INCH ALUMINUM DISK ATTACHED TO A 24 INCH
SECTION OF REBAR DRIVEN INTO THE GROUND (DUE TO THE DRIVING FORCE REQUIRED, IT
IS EXPECTED THE REBAR IS WEDGED INTO A CRACK IN THE ROCK).

TO REACH FROM THE INTERSECTION OF STATE HIGHWAYS 89 AND 160, PROCEED NORTH ON 89 UNTIL JUST NORTH OF MILE MARKER 505. TURN WEST AT DIRT ROAD WITH LARGE 5 FT. MASONRY STONE STRUCTURE. STAY ON MAIN ROAD UNTIL YOU GET TO THE END OF BODAWAY MESA ON YOUR LEFT AND SHINUMO ALTER IN THE DISTANCE ON THE RIGHT. TURN RIGHT AT THE Y BEFORE THE GAP BETWEEN BODAWAY MESA AND TOOTH ROCK, CONTINUE WEST FOR APPROX. 0.5 MILE. TURN LEFT AFTER POND/TANK STRUCTURE ON LEFT. TURN LEFT AT Y AND CONTINUE PAST AN INTERSECTION AND ANOTHER TURNOUT ON LEFT. TURN LEFT AT Y TO PASS A HOGAN ON LEFT, CONTINUE STRAIGHT THROUGH AN INTERSECTION WHERE YOU COULD VEER LEFT. ROADS SPLIT AND PARALLEL EACH OTHER - TAKE EITHER ROAD. WHEN THESE ROADS COVERGE VEER RIGHT QUICKLY DROPPING DOWN A ROUGH HILL TO A POND/TANK. STAY TO THE LEFT OF THE TANK, ALWAYS WITHIN VIEW OF THE TANK. THE ROAD CONTINUES DIRECTLY ON THE WEST SIDE OF THE TANK AND IS LOSEST TO THE TANK. TURN LEFT AT NEXT Y AND STAY ON ROCKY ROAD. GO STRAIGHT AT NEXT Y, TURN RIGHT AT NEXT Y. CONTINUE NW ON THIS ROAD FOR A FEW MILES PARALLELING AND FINALLY IN VIEW OF THE NORTH RIM. CONTINUE UNTIL YOU GET TO A PILE OF GRAVEL AND A CHOLLA CACTUS. TURN LEFT AT THE GRAVEL PILE AND STAY LEFT UNTIL THE LARGE 4 FT. CAIRN IS IN VIEW.



STATION NAME: "EMIN"
PID: "AJ5639"
JCLS IDENTIFIER: "EMIN"

Monument Location: The station is located on the Navajo Indian Reservation. From the small village of "The Gap" on Hwy 89 proceed north along Hwy 89 for 7.1 miles to entrance road on left just past mile marker 505. Entrance road is marked by large round rock structure that looks like a really big cairn. Turn left and proceed west for 6.8 miles along main road to west end of Bodaway Mesa and fork in main road (Shinumo Alter can be seen in the distance to the right). Take right fork and continue in a westerly direction along main road for 0.6 miles to a tank/pond structure on left and large metal tank on top of hill on your right. Veer left after tank/pond structure on left and proceed in a westerly direction for 0.9 miles to a fork in the road. Take the right fork and proceed westerly along rough road for 1.3 miles to another fork in the road. Take the left fork and proceed in a westerly direction for 3.0 miles past an Indian Hogan on the left to a tank/pond. Drop down a the rough hill, through the tank/pond and up the rough hill on the other side continue along the rough road for 2.2 miles to another fork in the road and a small cairn on the right. Take the right fork and follow the road westerly and then NW along the Canyon Rim for 3.6 miles to a dim fork to the left with a pile of gravel and a cholla cactus next to it. Turn left at this fork onto dim road and go 0.1 miles crossing over ridge (Canyon is now in clear view to the west). Turn left after crossing over ridge and proceed 0.1 miles to end of trail and station on the left.

Monument Description: Aluminum Marker stamped "EMIN GCMRC 01"

**Date:** May 2003

Monument Established By: GRANCN

#### Published NAD 83 (2001 FBN Arizona) Geodetic Position

Lat. 36 24 12.03777 N Long. 111 49 51.09660 W

#### Published ELLIP Height (2001 FBN Arizona)

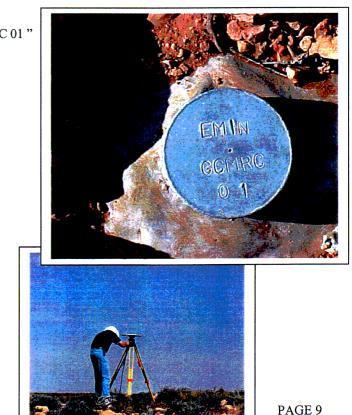
Height = 1742.567 m

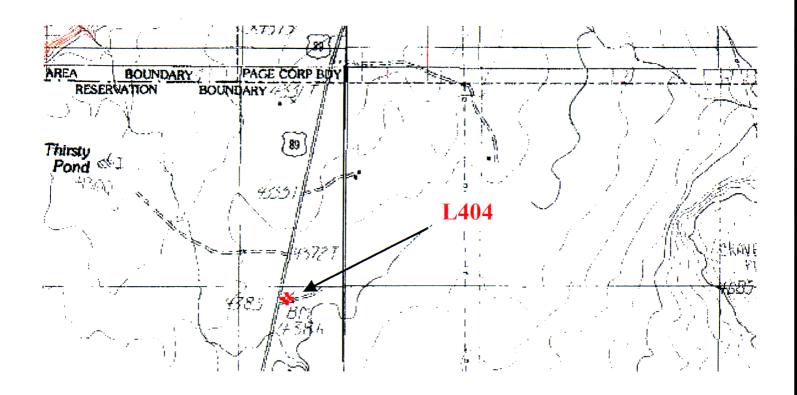
#### Adjusted NAD 83 (2001 FBN Arizona) Geodetic Position

Lat. 36 24 12.03777 N Long. 111 49 51.09660 W

#### Adjusted ELLIP Height (2001 FBN Arizona)

Elevation = 1742.567 m





STATION NAME: "L 404"
PID: "GP0283"
JCLS IDENTIFIER: "L404"

**Monument Location:** To reach the station from the intersection of Hwy 89 & Hwy 89A, south of the town of Page, AZ., proceed northerly on Hwy 89 for approximately 19.5 miles to a paved entrance and a fence on the right and the station on the easterly side of the fence. The station is also just north of mile marker 544.

Monument Description: Set in top of a concrete monument and stamped "L 404 1962"

**Date:** May 2003

Monument Established By: CGS

#### Published NAD 83 (2001 FBN Arizona) Geodetic Position

Lat. 36 51 58.31235 N Long. 111 30 12.23455 W

#### Published ELLIP Height (2001 FBN Arizona)

Height = 1314.441 m

#### Adjusted NAD 83 (2001 FBN Arizona) Geodetic Position

Lat. 36 51 58.31235 N Long. 111 30 12.23455 W

#### Adjusted ELLIP Height (2001 FBN Arizona)

Elevation = 1314.377 m





# National Geodetic Survey, Retrieval Date = JUNE 5, 2003

FBN - This is a Federal Base Network Control Station.

DESIGNATION - L 404 = "L404"

PTD - GP0283

STATE/COUNTY- AZ/COCONINO

USGS QUAD - LEES FERRY (1985)

#### \*CURRENT SURVEY CONTROL

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

NAD 83(1992)-	36 51 58.31254	(N) 111	30 12.23396	(W)	ADJUSTED
NAVD 88 -	1337.778	(meters)	4389.03	(feet)	ADJUSTED
<del>x</del> -	-1,873,091.194	(meters)			COMP
Υ -	-4,754,292.058	(meters)			COMP
z -	3,806,312.455	(meters)			COMP
LAPLACE CORR-	1.29	(seconds)			DEFLEC99
ELLIP HEIGHT-	1314.37	(meters)	(09	/30/99)	GPS OBS
GEOID HEIGHT-	-23.41	(meters)	4),		GEOID99
DYNAMIC HT -	1336.228	(meters)	4383.94	(feet)	COMP
MODELED GRAV-	979,426.7	(mgal)			NAVD 88
HORZ ORDER -	A				
VERT ORDER -	FIRST CLASS	S II			
ELLP ORDER -	THIRD CLASS	SI			

The horizontal coordinates were established by GPS observations and adjusted by the National Geodetic Survey in September 1992.

The orthometric height was determined by differential leveling and adjusted by the National Geodetic Survey in June 1991.

The X, Y, and Z were computed from the position and the ellipsoidal ht.

The Laplace correction was computed from DEFLEC99 derived deflections.

The ellipsoidal height was determined by GPS observations and is referenced to NAD 83.

The geoid height was determined by GEOID99.

The dynamic height is computed by dividing the NAVD 88 geopotential number by the normal gravity value computed on the Geodetic Reference System of 1980 (GRS 80) ellipsoid at 45 degrees latitude (g = 980.6199 gals.).

The modeled gravity was interpolated from observed gravity values.

		North	East	Uni	ts Scale	Co	nverg.
SPC AZ C	- 650	702.437	250,206.	468 M	T 0.99991672	+0 1	4 52.6
UTM 12	- 4,080	0,147.696	455,131.	073 M	T 0.99962480	-0 1	8 07.3

#### SUPERSEDED SURVEY CONTROL

NAD 83(1992)-	36 51 58.31358(N)	111 30 12.23214(W)	AD (	) B
ELLIP HT -	1314.42 (m)	(09/30/92)	GP (	) 2 1

Superseded values are not recommended for survey control. NGS no longer adjusts projects to the NAD 27 or NGVD 29 datums. See file dsdata.txt to determine how the superseded data were derived.

U.S. NATIONAL GRID SPATIAL ADDRESS: 12SVF5513180148 (NAD 83)

MARKER: DB = BENCH MARK DISK

SETTING: 7 = SET IN TOP OF CONCRETE MONUMENT

STAMPING: L 404 1962

MARK LOGO: NONE

MAGNETIC: N = NO MAGNETIC MATERIAL

STABILITY: C = MAY HOLD, BUT OF TYPE COMMONLY SUBJECT TO

STABILITY: SURFACE MOTION

SATELLITE: THE SITE LOCATION WAS REPORTED AS SUITABLE FOR

SATELLITE: SATELLITE OBSERVATIONS - June 07, 1999

HISTORY	-	Date	Condition	Report By
HISTORY	-	1962	MONUMENTED	CGS
HISTORY	-	1983	GOOD	NGS
HISTORY		19920203	GOOD	NGS
HISTORY	-	19951211	GOOD	CHANCE
HISTORY	-	19981119	GOOD	NGS
HISTORY	_	19981119	GOOD	NGS
HISTORY	-	19990426	GOOD	NGS
HISTORY	-	19990607	GOOD	NGS
HISTORY	_	2003	GOOD	JCLS

#### STATION DESCRIPTION

DESCRIBED BY COAST AND GEODETIC SURVEY 1962 5.75 MI S FROM PAGE.

ABOUT 5.75 MILES SOUTH ALONG U.S. HIGHWAY 89 FROM THE NORTHEAST END OF THE GLEN CANYON BRIDGE AT PAGE, ARIZONA. 239 FEET NORTHEAST OF HIGHWAY, MILEPOST NUMBER 544, 125 FEET EAST OF THE CENTERLINE OF THE HIGHWAY, 20 FEET NORTH-NORTHWEST OF THE CENTERLINE OF A PRIVATE TRACK ROAD, 2.0 FEET EAST OF A METAL WITNESS POST, ABOUT 3 1/2 FEET ABOVE THE LEVEL OF THE HIGHWAY, AND SET IN THE TOP OF A CONCRETE POST PROJECTING 6 INCHES.

#### STATION RECOVERY (1983)

RECOVERY NOTE BY NATIONAL GEODETIC SURVEY 1983
RECOVERED IN GOOD CONDITION. ADD--6.5 METERS (21.5 FT) EAST OF THE RIGHT OF WAY
FENCE.

#### STATION RECOVERY (1992)

RECOVERY NOTE BY NATIONAL GEODETIC SURVEY 1992

THE STATION IS LOCATED ABOUT 9.3 KM (5.8 MI) SOUTH OF THE GLEN CANYON BRIDGE LOCATED AT PAGE, 6.1 KM (3.8 MI) SOUTH OF THE JUNCTION OF U.S. HIGHWAY 89L LEADING EAST AND U.S. HIGHWAY 89 LEADING SOUTH NEAR THE SOUTHWEST EDGE OF PAGE, AT MILE POST 544, AND AT THE EAST SIDE OF THE EAST RIGHT-OF-WAY FENCE OF THE HIGHWAY. OWNERSHIP--PRESUMED TO BE THE NAVAJO NATION.

TO REACH THE STATION FROM THE NORTHEAST END OF THE GLEN CANYON BRIDGE LOCATED NEAR THE NORTHWEST EDGE OF PAGE, GO SOUTH ON HIGHWAY 89 FOR 9.3 KM (5.8 MI) TO MILE POST 544, THE STATION ON THE LEFT AND A NAVAJO INDIAN RESERVATION MARKER ON THE RIGHT. THE STATION IS A STANDARD DISK SET IN THE TOP OF A CONCRETE POST PROJECTING 7 CM ABOVE THE GROUND. LOCATED 73.0 M (239.5 FT) NORTHEAST OF MILE POST 544, 38.0 M (124.7 FT) EAST OF THE CENTERLINE OF THE HIGHWAY, 6.5 M (21.3 FT) EAST OF RIGHT-OF-WAY FENCELINE, 6.5 M (21.3 FT) EAST OF A FIBERGLASS WITNESS POST, 6 M (19.7 FT) NORTHEAST OF THE CENTER OF A DIM TRACK ROAD AND 0.91 M (2.99 FT) ABOVE THE LEVEL OF THE HIGHWAY.

#### STATION RECOVERY (1995)

RECOVERY NOTE BY JE CHANCE AND ASSOCIATES 1995 (MFY)
RECOVERED AS DESCRIBED AND IN GOOD CONDITION THE WITNESS POST HAS BEEN MOVED IN
LINE WITH FENCELINE

STATION RECOVERY (1998)

RECOVERY NOTE BY NATIONAL GEODETIC SURVEY 1998 (CSM)
RECOVERED AS DESCRIBED. LOCATED 0.08 KM (0.05 MI) NORTHWEST OF US HIGHWAY 89
MILEPOST 544.

STATION RECOVERY (1998)

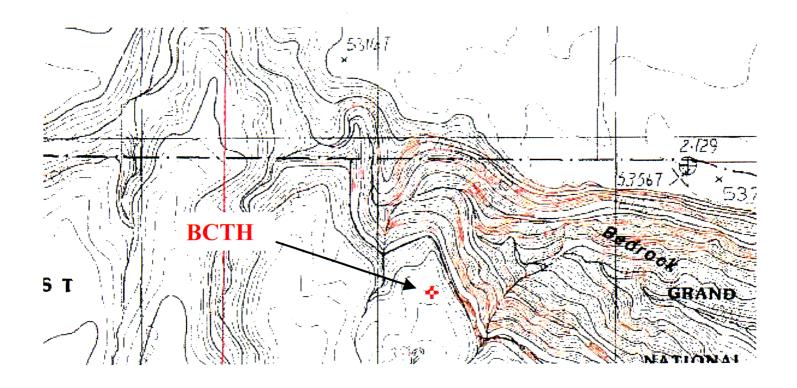
RECOVERY NOTE BY NATIONAL GEODETIC SURVEY 1998 RECOVERED IN GOOD CONDITION.

STATION RECOVERY (1999)

RECOVERY NOTE BY NATIONAL GEODETIC SURVEY 1999 (CSM) RECOVERED AS DESCRIBED.

STATION RECOVERY (1999)

RECOVERY NOTE BY NATIONAL GEODETIC SURVEY 1999 (CSM) RECOVERED AS DESCRIBED.



STATION NAME: "BCTH"
JCLS IDENTIFIER: "BCTH"

Monument Location: To reach "BCTH" from the Marble Canyon Lodge in Marble Canyon, AZ, travel westerly on Hwy 89A for approx 21.4 miles to a gravel road to the left leading to the House Rock Wildlife Area. Turn left and precede southerly on main road for approx. 18.9 miles to a gravel road on the left (632) leading to the Wildlife Area Headquarters. Turn left and precede ENE for approx. 1.9 miles to a gravel trail on the right leading to South Canyon Trail. Turn right and precede easterly for approx. 1.1 miles to a barbed wire gate. Pass through gate and take an immediate left on dirt trail and proceed along fence for approx. 0.2 miles to a y-intersection, bear right for an additional 2.8 miles to the end of the trail and the station straight ahead on the Bedrock Canyon rim. The station is a pk-nail set in a boulder.

**Monument Description:** PK Nail

**Date:** May 2003

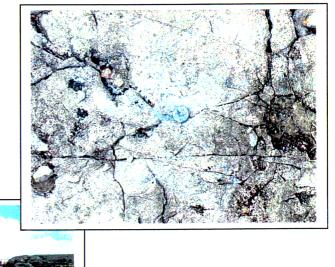
Monument Established By: JCLS

### Adjusted NAD 83 (2001 FBN Arizona) Geodetic Position

Lat. 36 30 24.58059 N Long. 111 54 06.58988 W

Adjusted ELLIP Height (2001 FBN Arizona)

Elevation = 1611.524 m



# National Geodetic Survey, Retrieval Date = JUNE 5, 2003

\*

CORS - This is a GPS Continuously Operating Reference Station.

DESIGNATION - FREDONIA CORS L1 PHASE CENTER = "FRED"

CORS\_ID - FRED
PID - A18806
STATE/COUNTY- AZ/COCONINO

USGS QUAD - SHINARUMP POINT (1988)

#### \*CURRENT SURVEY CONTROL

NAD 83 (CORS) - NAVD 88 -	36 59 17.97783	(N) 112 29	57.13531(W)	ADJUSTED
EPOCH DATE -	2002.00			
X -	-1,952,383.614	(meters)		COMP
Υ -	-4,713,656.162	(meters)		COMP
z -	3,817,279.491	(meters)		COMP
ELLIP HEIGHT-	1530.75	(meters)	(03/??/02)	GPS OBS
GEOID HEIGHT-	-22.11	(meters)		GEOID99
HORZ ORDER -	SPECIAL (CORS)			
ELLP ORDER -	SPECIAL (CORS)			

ITRF positions are available for this station. The coordinates were established by GPS observations and adjusted by the National Geodetic Survey in March 2002. The coordinates are valid at the epoch date displayed above. The epoch date for horizontal control is a decimal equivalence of Year/Month/Day.

The PID for the CORS ARP is AI8805.

The XYZ, and position/ellipsoidal ht. are equivalent.

The ellipsoidal height was determined by GPS observations and is referenced to NAD 83.

The geoid height was determined by GEOID99.

```
North East Units Scale Converg. SPC AZ C - 664,333.413 161,504.367 MT 0.99993312 -0 21 01.8
```

#### SUPERSEDED SURVEY CONTROL

```
NAD 83(CORS) - 36 59 17.97834(N) 112 29 57.13541(W) AD(1997.00) c

ELLIP HT - 1530.75 (m) (09/??/01) GP(1997.00) c c

NAD 83(CORS) - 36 59 17.98709(N) 112 29 57.13532(W) AD(1997.00) c

ELLIP HT - 1530.96 (m) (12/??/00) GP(1997.00) c c
```

Superseded values are not recommended for survey control. NGS no longer adjusts projects to the NAD 27 or NGVD 29 datums. See file dsdata.txt to determine how the superseded data were derived.

U.S. NATIONAL GRID SPATIAL ADDRESS: 12SUF6658294628(NAD 83) MARKER: STATION IS THE L1 PHASE CENTER OF THE GPS ANTENNA

### STATION DESCRIPTION

DESCRIBED BY NATIONAL GEODETIC SURVEY STATION IS A GPS CORS. LATEST INFORMATION INCLUDING POSITIONS AND VELOCITIES ARE AVAILABLE IN THE COORDINATE AND LOG FILES ACCESSIBLE BY ANONYMOUS FTP OR THE WORLDWIDE WEB.

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# 6.0 COPY OF SCOPE OF WORK

#### SCOPE OF WORK

Precision Airborne LIDAR Surveys
Grand Canyon Research & Monitoring Center
Erosion and Sedimentation sites
John Chance Land Surveys
Lafayette, LA
Contract No. DACW43-02-D-0505
Delivery Order No. 0007

# 1. Description of Work:

The Contractor shall collect digital elevation data from a precision airborne (LIDAR) survey along two projects in Northern Arizona for the Grand Canyon Monitoring & Research Center (GCMRC), USGS, in support of the erosion and sedimentation monitoring programs. The GCMRC requires very accurate digital terrain models (DTM's) to monitor erosion and sedimentation at 11 sites along the Colorado River in the Grand Canyon. This task order will test the technology on only two (2) sites. The approach will be to utilize portable FLI-MAP® technology and proprietary FLIP7® software to collect and process DTM data that will meet or exceed the GCMRC's specifications. The two project areas are (1) Eminence, and (2) South Canyon. It is not necessary to have the data orientation in the videos and Flip7 to be consistent for the surveys. The purpose of the surveys is to obtain a precise survey and develop a digital terrain model (DTM) of the projects to be surveyed for the purpose of determining volumes or obtaining other engineering data. The survey will be accomplished utilizing aerial topographic laser surveying techniques (LIDAR) to develop and identify all right of way characteristics and develop digital terrain models as necessary to obtain profiles of road crossings, piers, and other physical features

# 2. Information Supplied by the Government:

a. The Government will supply maps and coordinates of the two projects to be flown indicating all points of interest to be identified during the flight, and limits to be surveyed. The GCMRC has developed these maps:

Site 1 Eminence 3.1 miles in length
Site 2 South Canyon 2.8 miles in length

- b. Section A containing Data Standards and Delivery requirements.
- c. Section B containing minimum technical standards for GPS reference station occupations in the support of GCMRC control and remote sensing operations.

d. Section C containing special federal aviation regulation 50-2 and federal aviation regulation 93 subpart U, briefing for the Grand Canyon National Park Special Flight Rules Area.

# 3. Work to be Performed by the Contractor:

The Contractor shall provide equipment, supplies, aerial survey equipment and personnel, fully equipped to safely and expediently perform the following work:

- a. A precision laser airborne mapping system, similar to FLI-MAP or better shall be used to acquire topographic point elevation data and high-resolution color digital video image data simultaneously along the two projects: The FLI-MAP or Fast Laser Imaging-Mapping and Profiling system integrates an accurate GPS positioning system with video imaging and two scanning reflectorless laser rangefinders to provide fast and accurate aerial surveys. The system, aboard a specially equipped Bell 206L helicopter or similar, is flown over the corridors of interest collecting precise GPS, platform altitude, laser ranges, and imagery data. With a data collection rate of 10,000 ranges per second per laser, height above ground of 100 meters (dependent upon vertical change of terrain and hills), and an aircraft velocity of 45 miles per hour, data density is approximately 10 or more per square meter. This data density makes it possible to differentiate planimetric features by recognizing patterns of points with spatial relationships.
- b. The digital video image shall be recorded and digitized for correlation with the LIDAR data. Video shall be of highest quality and resolution available with the Fli-Map system. Digitized videos are required. An audio voice track shall also be included on the video with commentary to identify significant landmarks and aid in interpreting the laser images. The LIDAR scanning rate shall be approximately 16,000 points per second. Density of ground laser points shall be 10 per square meter or greater per laser. The flight altitude and speed shall be optimized to acquire the specified point density, resolution, and accuracy. The highest resolution, and absolute referenced elevation data is required. The airborne mapping system shall have an absolute accuracy of 15 centimeters horizontal and 10 centimeters vertical or better for LIDAR points.

The survey shall also include information to locate any structures, vegetation, and other shoreline features.

c. Basic horizontal control shall be established or recovered from the NGS database and be "B" order or better. A survey control plan shall be submitted to the U.S. Army Corps of Engineers (USACE) for approval by GRMRC before any field surveying is done. Any control points set shall be of a semi-permanent nature such as copperweld or re-bar type rods referenced for recovery by others. Once JCLS has mobilized to the project areas, local survey monumentation will be recovered to control the surveys and reference the FLI-MAP data to the desired horizontal coordinate system and vertical datum. (NAD 83/NAVD 88

Arizona State Plane Grid Coordinate System). Both vertical and horizontal survey control shall be in *meters*. The number of recovered monuments will vary depending upon the measured relative accuracy of the existing monuments recovered. A dual frequency GPS receiver will be used at each site to record pseudo range and carrier phase information for subsequent on-the-fly (OTF) kinematic post processing.

- d. It is necessary to have the projects flown after April 21, 2003 to assure vegetation is at a leaf-on condition. Close coordination for the flying dates must be maintained with the GCMRC, Flagstaff, AZ and/or the St. Louis District to insure the projects are flown during acceptable periods. Point of Contact with the GCMRC is Mr. Mike Liszewski, (928) 556-7458 or Mr. Phil Davis (928) 556-7133. Mr. Davis and Mr. Liszewski will be available during this time periods to assist in defining flight limits and boundaries in the field for all projects.
  - e. Data collection will be carefully planned to correspond with GPS windows of six or more satellites in view. Experience with continuous mass data collection has shown that careful tracking of the maximum number of GPS satellites is necessary to minimize data gaps or areas of less than acceptable data accuracy.
  - f. Flight operations will be coordinated with a client contact designated by GCMRC and JCLS ground support. Papillon Helicopters will provide a Bell 206 L-3 aircraft or equal from its Grand Canyon Village location. The pilot will maintain steerage by following preplanned flight lines. Sufficient passes will be made over each project area to ensure adequate cover of laser data at an altitude of 100 meters above the base of the canyon. Flight operations require permitting from the National Park Service and the GCRMC will assist in the necessary coordination and a pre-flight meeting with the National Park Service is required.
  - g. Logged GPS pseudo range and carrier data, the INS data, and the laser data will be downloaded from the helicopter computer after the flight. This data and that from the reference GPS receivers will then be input to a central processing computer and the data quality is then field-verified.

# 4. Methodology Specific to the Grand Canyon Project

The ability of the FLI-MAP system to achieve its normal level of accuracy (15 centimeters horizontal and 15 centimeters vertical) will depend on achieving an accurate OTF kinematic post-processed solution of the GPS data. This requires that the FLI-MAP system on board the helicopter, and the base stations, be able to interrogate a minimum number of GPS satellites (minimum of 5, ideally at least 6) at all times. The base of the Grand Canyon provides a challenging location for GPS reception. In order for JCLS to ascertain the ability to achieve satisfactory GPS reception at the 2 individual test project locations, the following steps will be taken:

- Each project location will be accurately transferred to a topographical map. The topographical maps contain elevation data for the project site and surrounding terrain.
- Cross sections will be cut at each location in order to determine the slope angles of the canyon walls.
- Masks will be generated for each site, depicting the area of the sky that we estimate will be obscured by terrain at the helicopter's operating altitude.
- The masks will be been combined with known GPS satellite orbits to determine time windows when it is anticipated that sufficient GPS satellites will be visible to the FLI-MAP system at each location.

# **Data Processing**

Due to data formats and processing algorithms, all of the data from each flight is pre-processed to produce three-dimensional positions of the laser returns. The GPS data from the base stations and the primary navigation receiver on the helicopter are reduced to produce vector offsets from all of the base stations to the helicopter. Least squares techniques are then utilized to determine a "best fit" three-dimensional position of the helicopter every one half second. The GPS data from the two on-board GPS receivers are also reduced kinematically to produce helicopter heading results every one half second. This position and attitude information is then time matched with the inertial and laser data to produce accurate XYZ's of the laser returns.

# **Accuracy of Captured Data**

The absolute accuracy of discrete laser points (representing ground and feature data points) with FLI-MAP using OTF kinematic positioning is 0.5' (15 cm) horizontally and 0.5' (15 cm) vertically. The relative accuracy of data points collected with subsequent scans and to the kinematic control network is 0.35' horizontally and 0.25' vertically. The relative accuracy of points common to a single scan is 0.2'. The stated accuracies are to the 95% confidence level.

### 5. Deliverables:

- a. A survey narrative shall be produced in the form of a letter type report detailing all aspects of the LIDAR flight, including a description of the fieldwork and detailed office data processing procedures. The description shall include location, navigation and control, operations, all survey logs and data sheets used, any difficulties with the survey, and the method of resolution of the difficulties shall be documented. Two copies of the report for each of the two projects shall be provided.
- b. The contractor shall provide an interpretation and analysis of the results of the survey, including data quality, coverage of the area, and a summary of the findings. This summary shall be included in the transmittal letter documenting the electronic data delivered as a result of the survey. Two copies for each project shall be provided.

- c. Fli-Map laser data will be delivered on DVD with the latest version of the FLIP-7 software. Upgrades to FLIP-7 software may be necessary for current users. Also, high-resolution color digital video imagery (360 x 240 pixels) that is time coded to the Fli-Map data will be delivered of the entire route in mpeg format. Three videos should be submitted including forward and down perspective with the third video being a digitized double zoom down video. Two copies of the Fli-Map laser data and digital video imagery shall be submitted on DVD. Additionally, two copies of ASCII data for the entire project shall be submitted on CD-ROM for use within other software that may not read the FLIP 7 compressed data format.
- d. Two copies of two data sets are required. Both a cleaned and edited raw Fli-Map data set and a thinned to approximately 5% data set shall be delivered in ASCII format. The entire data set shall be filtered to produce a bare earth model and delivered in ASCII format. ASCII data file size shall be no greater than 200,000 points. Both a hard copy and digital index of the data file shall be produced.
- e. The contractor will provide up to 24 hours of training for up to sixt (6) engineers or technicians or their representatives in the use of FLIP-7 software. The training will be conducted at the Contractors Office location. Transportation costs and per diem costs will be paid by Government personnel attending the training. Flip-7 technical support shall be provided for 24 hours of help (for each engineer or technician) by telephone over a one-year period. Responses to requests for technical support shall be made during normal business hours within 2 business days of initial inquiry. New releases or upgrades of the FLIP 7 software shall be provided to the St. Louis District of the U.S. Army Corps of Engineers and the GCMRC, Flagstaff, AZ at no cost of the Government for a period of one year.
- f. A metadata file at least minimally compliant with the Federal Geographic Data Committee (FGDC) Content Standards for Digital Geospatial Metadata. The COE will provide a Metadata generation package (CORPSMET) to generate these files upon request by the Contractor or the Contractor can use software of their choice as long as the FGDC compliant Metadata is produced as specified in 2.b above.

JCLS will deliver 2 copies of the following information to GCMRC:

- 100% raw data XYZ ASCII File from the FLI-MAP Data.
- 100% cleaned bare earth XYZ ASCII File from the FLI-MAP Data.
- 100% processed all points.
- All raw Fli-Map project files.
- 5% thinned ASCII File (exact percentage coordinated with GCRMC).
- Digital Video delivered on DVD Forward and Down Perspective

# Survey Control Report

JCLS will begin preparation of deliverables upon completion of data collection. A time estimate for delivery of the final product will be less than 20 business days (exception for FLIP7 training, which is to be defined by client) after completion of the flights.

## 5. Schedule and Submittal:

The contractor shall prepare and submit all deliverables and pertinent data, at no cost to the Government, to the U.S. ENGINEER DISTRICT, ST. LOUIS, CEMVS-ED-S (Attn: Robert D. Mesko), 1222 Spruce St., St. Louis, MO 63103-2833 before July 30, 2003.

# 6. Time Extension

In the event these schedules are exceeded due to causes beyond the control and without fault or negligence of the contractor, as determined by the Contracting Officer, this delivery order completion date will be extended one (1) calendar day for each day of delay.

Requests for time extensions for an individual task order should be forwarded to the Contracting Officer no later than fourteen (14) days preceding the completion date shown on the task order.